

CENTRE FOR INTELLIGENT MACHINES (CIM)

Centre de recherche sur les machines intelligentes

www.cim.mcgill.ca

Annual Report 2011

Director

Professor Benoit Boulet

boulet@cim.mcgill.ca

SUMMARY	3
Section I – MEMBERSHIP	
Section II – HONOURS and AWARDS	7
Section II – PUBLICATIONS	8

SUMMARY

The McGill Centre for Intelligent Machines (CIM) is a multi-disciplinary, inter-departmental, inter-faculty research group formed in 1985 to provide an enriched mentoring and training environment for graduate students studying in the field of robotics and intelligent systems.

For close to 3 decades, CIM has been a pioneering force in cross-disciplinary research. The Centre is primarily located in contiguous space where labs and student offices are shared. CIM's membership and students have been universally recognized over the years for their highest standards of excellence - exceptional scientific achievements and outstanding contributions to society and industry.

CIM's management design and organizational structure have been studied, emulated and adopted by various units, both within the university and outside of McGill, notably in the academic sector. CIM continues to be regarded by its peers as a model for "best practices" in a world now heavily populated by research organizations.

CIM recently celebrated its 25th Anniversary with an international guest speaker series and a scientific symposium.

For the year 2011:

The Centre was comprised of 19 members from both the Faculties of Engineering and Science --the Department of Electrical and Computer Engineering, Department of Mechanical Engineering and the School of Computer Science. CIM also has 13 associate members representing a diversity of research collaborations, such as within the Faculty of Medicine -- the Royal Victoria Hospital and the Montreal Neurological Institute.

The Centre was home to a diverse population of about 160 graduate students, post-docs, research assistants and associates, as well as visiting scholars and undergraduate students from various disciplines.

PhD	Master's	U/Grads	Post-	
			Docs	
69.5	48.5	16	11	145

The CIM members were collaborators and co-collaborators in grants and contracts totally about \$600M.

		PI	Co-PI
Total Value	е	7M	555M

REPARTI - Regroupement pour l'étude des environnements partagés intelligents répartis

http://reparti.gel.ulaval.ca/en/REPARTI/index.chtml (website currently under reconstruction)

Centre REPARTI is a \$2.4M inter-institutional, interdisciplinary collaborative venture comprised of 8 Quebec institutions, 33 members and over 200 students. The McGill node of REPARTI is represented by 14 members from the McGill Centre for Intelligent Machines (CIM). The members of the McGill node collaborate in grants and contracts valued in excess of \$5M. The institutions participating in REPARTI are - Université Laval (host institution), Université de Sherbrooke, Ēcole Polytechnique, Université de Montréal, Université du Québec à Rimouski, Université du Québec à Chicoutimi and École de technologie supérieure (ÉTS).

Supported by the Quebec government's *Fonds de recherche Nature et technologies (FRNT*), this regroupement stratégique builds on some unique precedents:

(1) The historical and concrete partnership that developed over the past 25 years between prominent researchers in U. Laval and McGill (CIM) as a result of the NSERC National Centres of Excellence program, the interuniversity-industrial consortium IRIS-Precarn, and the FQRNT Réseau QERRAnet.

(2) The long and productive relationship established between the McGill Centre for Intelligent Machines (CIM) and the Quebec government through the former FCAR Centre de recherche programme.

The formal renewal process for REPARTI will begin in the year 2012.

NEW MEMBERS

**Professor Aditya Mahajan became a member of CIM in 2011

Professor Mahajan is an assistant professor in the Department of Electrical and Computer Engineering. He is a graduate of the University of Ann Arbour, Michigan, where he completed his PhD in Electrical and Computer Engineering in 2008, and then went on to complete a post-doctoral fellowship at Yale University.

The main focus of Dr. Mahajan's research is to develop an axiomatic framework for sequential decision making in decentralized multi-agent systems. Such systems arise in almost all technological systems including control systems, communication systems, sensor networks, and robotics.

**Professor James Richard Forbes became a new associate member of CIM in 2011

Dr. Forbes is an assistant professor in the Department of Mechanical Engineering. He completed a B.A.Sc. in Mechanical Engineering from the University of Waterloo and went on to complete both a M.A.Sc. Aerospace Science and Engineering and a PhD Aerospace Science and Engineering from the University of Toronto.

Dr. Forbes studies control and estimation techniques for mechanical, aerospace, and robotic systems. In particular, his interests lie in vibration control, spacecraft attitude control, the control of (flexible) robotic manipulators, and mobile robot localization. His research focuses on fundamental theoretical developments, as well as the application of new and existing control theories to practical, real-world problems, as well as synthesis of controllers, for example, robust yet optimal controllers, using numerical techniques. Professor Forbes' research is primarily motivated by (but not exclusively) aerospace problems; he seeks to develop better control and estimation techniques thus enabling Earth science, astronomy, and the commercial development of the Canadian aerospace industry.

Section I – MEMBERSHIP

FULL MEMBERS

Name	Title	Department	Office	Phone	Email
Angeles, Jorge	Professor	Mechanical Engineering	Workman 452	(514) 398-6315	angelesATcimDOTmcgillDOTca
Arbel, Tal	Associate Professor	Electrical and Computer Engineering	McConnell 425	(514) 398-8204	arbelATcimDOTmcgillDOTca
Boulet, Benoit	Associate Professor	Electrical and Computer Engineering	McConnell 509	(514) 398-1478	bouletATcimDOTmcgillDOTca
Caines, Peter	Professor	Electrical and Computer Engineering	McConnell 512	(514) 398-7129	petercATcimDOTmcgillDOTca
Clark, James	Professor	Electrical and Computer Engineering	McConnell 422	(514) 398-2654	clarkATcimDOTmcgillDOTca
Cooperstock, Jeremy	Associate Professor	Electrical and Computer Engineering	McConnell 424	(514) 398-5992	jerATcimDOTmcgillDOTca
Cortelezzi, Luca	Associate Professor	Mechanical Engineering	McConnell 369	(514) 398-6299	crtlzATcimDOTmcgillDOTca
Dudek, Gregory	Professor	Computer Science	McConnell 419	(514) 398-4325	dudekATcimDOTmcgillDOTca
Ferrie, Frank	Professor	Electrical and Computer Engineering	McConnell 441	(514) 398-6042	ferrieATcimDOTmcgillDOTca
Kovecses,	Associate	Mechanical	Macdonald	(514)	kovecsesATcimDOTmcgillDOTca
Jozsef	Professor	Engineering	163	398-6302	
Langer,	Associate	Computer Science	McConnell	(514)	langerATcimDOTmcgillDOTca
Michael	Professor		329	398-3740	
Levine, Martin	Professor	Electrical and Computer Engineering	Workman 451	(514) 398-7115	levineATcimDOTmcgillDOTca
Mahajan, Aditya	Assistant Professor	Electrical and Computer Engineering	McConnell 533	(514) 398-4470	adityaDOTmahajanATmcgillDOTca
Michalska, Hannah	Associate Professor	Electrical and Computer Engineering	McConnell 514	(514) 398-3053	hannah DOT michalska AT mcgill DOT ca
Nahon, Meyer	Professor	Mechanical Engineering	McConnell 421	(514) 398-2383	mnahonATcimDOTmcgillDOTca
Pineau, Joelle	Associate Professor	Computer Science	McConnell 106N	(514) 398-5432	jpineauATcsDOTmcgillDOTca
Sharf, Inna	Associate Professor	Mechanical Engineering	McConnell 214	(514) 398-1711	isharfATcimDOTmcgillDOTca
Siddiqi, Kaleem	Professor	Computer Science	McConnell 420	(514) 398-3371	siddiqiATcimDOTmcgillDOTca
Zsombor- Murray, Paul	Associate Professor	Mechanical Engineering	Workman 454	(514) 398-6311	paulATcimDOTmcgillDOTca

ASSOCIATE MEMBERS	
-------------------	--

Name	Title	Unit	Office	Phone	Email
Cecere, Renzo	Associate	Cardiac Surgery	RVH S8-44	(514)	renzoDOTcecereATmuhcDOTmcgill
	Professor	(RVH)		843-1463	DOTca
Collins, Louis	Associate	Neurology and	MNI WB-315	(514)	louisDOTcollinsATmcgillDOTca
	Professor	Neurosurgery/Bio		398-4227	
		medical			
		Engineering			
Forbes, James	Assistant	Mechanical	Macdonald	(514)	jamesDOTrichardDOTforbesAT
Richard	Professor	Engineering	156	398-9675	mcgillDOTca
Hayward,	Professor	Electrical and	McConnell	(514)	haywardATcimDOTmcgillDOTca
Vincent		Computer	440	398-5006	
		Engineering			
Husty,	Professor	Geometry and		+43-512-	manfred DOT husty ATuibk DOT
Manfred		CAD, University of		507/683	acDOTat
		Innsbruck, Austria		0	
Kry, Paul	Assistant	Computer Science	McConnell	(514)	kryATcsDOTmcgillDOTca
	Professor		113N	398-2577	
Liu, Xue	Assistant	Computer Science	Macdonald	(514)	xueliuATcsDOTmcgillDOTca
	Professor		318	398-1819	
Misra, Arun	Professor	Mechanical	Workman 455	(514)	misraATcimDOTmcgillDOTca
		Engineering		398-6288	
Mongrain,	Associate	Mechanical	Macdonald	(514)	rosaireDOTmongrainATmcgillDOT
Rosaire	Professor	Engineering	369	398-1576	са
Musallam, Sam	Assistant	ECE/Dept. of	McConnell	(514)	samDOTmusallamATmcgillDOTca
	Professor	Physiology	645	398-1702	
Panangaden,	Professor	Computer Science	McConnell	(514)	prakashATcsDOTmcgillDOTca
Prakash			108	398-7074	
Pike, Bruce	Professor	Neurology and	MNI WB-315	(514)	bruceDOTpikeATmcgillDOTca
		Neurosurgery/Bio		398-1929	
		medical			
		Engineering			
Precup, Doina	Associate	Computer Science	McConnell	(514)	dprecupATcsDOTmcgillDOTca
	Professor		326	398-6443	

Section II – HONOURS AND AWARDS

* CIM founding Director, **Professor Martin D. Levine**, awarded a *Canadian Academy of Engineering CAE Fellow* in June 2011 in Vancouver. CAE recognizes Professor Levine for being a pioneer of computer-based image processing techniques and computer vision.

* CIM-REPARTI member **Professor Frank Ferrie** received the Award for Research Excellence from the *Canadian Image Processing and Pattern Recognition Society CIPPRS/ACTIRF*, held during the 8th Annual *Canadian Conference on Computer and Robot Vision (CRV 2011)*, May 25-May 27, 2011 in St. John's Newfoundland.

*CIM-REPARTI member **Professor Jim Clark** was awarded *Outstanding Reviewer Award, 2011 International Conference on Computer Vision (ICCV)*, held in November 2011 in Barcelona Spain.

*CIM-REPARTI member **Professor Aditya Mahajan** received the *Peter Silvester Faculty Research Award* awarded by the Department of Electrical and Computer Engineering, February 2011.

*CIM-REPARTI member **Professor Gregory Dudek** was the recipient of the following:

- > Fessenden Professorship award in December 2010 for Science Innovation (held throughout 2011)
- the CS/EMB/RA Joint Societies Chapter of IEEE Kingston Section award of appreciation for Technical Presentation on October 27, 2011
- McGill Bravo 2011 Award-Winning Researchers honoree on May 5, 2011 for exceptional recognition in the previous year.

CIM in the MEDIA

* CIM - REPARTI member **Professor Joelle Pineau's** work on the Smartwheeler, a smart wheel chair that is designed to help people with disabilities get around, is featured in the *Summer 2011 edition of McGill Headway* magazine. <u>http://publications.mcgill.ca/headway/section/workspace/</u>

* CIM-REPARTI members **Professors Gregory Dudek** and **Philippe Giguère** (U. Laval), and members of the Mobile Robotics Lab, featured in *Canal Savoir June 2011. Canal Savoir: Aqua - le robot sous-marin.* http://www.canal.qc.ca/emission.php?id=10113

* CIM-REPARTI member **Professor Tal Arbel** and her group in the Medical Imaging Lab featured in *Faculty* of Engineering's Dean's Report - Fall 2011 - bio-engineering is booming at McGill! http://publications.mcgill.ca/engineering/2011/12/28/bioengineering-is-booming-at-mcgill/

* CIM-REPARTI PhD graduate student **Carmen Au's** work, under the supervision of *Professor Jim Clark*, was featured in *New Scientist* recently -- *Find your way around in a world of virtual mirrors 9 September* 2011. <u>http://www.newscientist.com/blogs/onepercent/2011/09/find-your-way-around-in-a-worl.html</u>

*CIM-REPARTI student, **Yogesh Girdhar**, PhD candidate under the supervision of *Professor Gregory Dudek*, was featured in the *McGill Reporter*, *November 2011*, in an article entitled "*Teaching Robots How to be Surprised*" <u>http://publications.mcgill.ca/reporter/2011/11/teaching-robots-how-to-be-surprised/</u>

Section II – PUBLICATIONS

PUBLICATIONS - Department of Electrical and Computer Engineering

ARBEL, Tal

Articles in refereed publications

• K. Murphy, ..., D. De Nigris, D. L. Collins, T. Arbel, et. al., "Evaluation of Registration Methods on Thoracic CT: The EMPIRE10 Challenge", IEEE Transactions on Medical Imaging, Vol. 30, Issue 11, pp. 1901-1920, Nov. 2011.

• M. Shah, Y. Xiao, N. Subbanna, S. Francis, D. L. Arnold, D. L. Collins, and T. Arbel, "Evaluating Intensity Normalization on MRIs of Human Brain with Multiple Sclerosis", Medical Image Analysis, Volume 15, Issue 2, pp. 267-282, April 2011.

• C. Laporte and T. Arbel, "Learning to estimate out-of-plane motion in ultrasound imagery of real tissue", Medical Image Analysis, Volume 15, Issue 2, pp. 202-213, April 2011.

Papers in Refereed Conference Proceedings

• M. Demirkus, B. Oreshkin, J. Clark, and T. Arbel, "Spatial and probabilistic codebook template based head pose estimation from unconstrained environments", 2011 IEEE International Conference on Image Processing (ICIP 2011), Brussels, Belgium, Sept. 2011.

• N. Subbanna, S. Francis, D. Precup, D.L. Collins, D. L. Arnold and T. Arbel, "Adapted MRF Segmentation of MS Lesions Using Local Contextual Information", Conference on Medical Image Understanding and Analysis (MIUA '11), London, U.K., July 2011.

BOULET, Benoit

Articles in refereed publications

H. Azarnoush, S. Vergnole, B. Boulet, and G. Lamouche, "Real-time Control of Angioplasty Balloon Inflation Based on Feedback from Intravascular Optical Coherence Tomography: Preliminary Study on an Artery Phantom," IEEE Transactions on Biomedical Engineering, 10.1109/TBME.2011.2172685

[2] V. Raissi Dehkordi and B. Boulet, Robust Controller Order Reduction, International Journal of Control, Vol. 84, No. 5, May 2011, pp. 985–997. Other refereed contributions

3] M. M. I. Chy and B. Boulet, "Development of an Improved Mathematical Model of the Heating Phase of Thermoforming Process" IEEE Industrial Application Society Annual Meeting, Orlando, Florida, Oct 9-13, 2011.

[4] M. M. I. Chy and B. Boulet, "Estimation and control of temperature profile over a sheet in thermoforming process using non-equidistant temperature sensor" IEEE Industrial Application Society Annual Meeting, Orlando, Florida, Oct 9-13, 2011.

[5] R. Modirnia and B. Boulet, "Model-Based Virtual Sensors and Core Temperature Observers in Thermoforming Applications" IEEE Industrial Application Society Annual Meeting, Orlando, Florida, Oct 9-13, 2011.

[6] A. Haddadi, A. Shojaei and B. Boulet, "Enabling High Droop Gain for Improvement of Reactive Power Sharing Accuracy in an Electronically-Interfaced Autonomous Microgrid" 2011 IEEE Energy Conversion Congress and Exposition, Phoenix, Arizona, Sept 17-22, 2011.

[7] M. M. I. Chy, A. Haidar and B. Boulet, "A model predictive controller of plastic sheet temperature for a thermoforming process" American Control Conference, June 29-July 1, 2011, San Francisco, California, pp. 4410-4415.

[8] A. Salehiomran, S. R. Modirnia, B. Boulet, M. Rochette,
"Single-longitudinal-mode fiber optic parametric oscillator based on
Smith predictor control scheme" Photonics North 2011, Ottawa, Canada,
May 16, 2011, Proc. SPIE 8007, 80070E (2011); doi:10.1117/12.905717

[9] H. Azarnoush, S. Vergnole, B. Boulet, and G.Lamouche, Optical coherence tomography layer thickness characterization of a mock artery during angioplasty balloon inflation, Proc. SPIE, Feb. 15, 2011, 7963, 796328 (2011); doi:10.1117/12.877995

[10] G. Lamouche, H. Azarnoush, S. Vergnole, V. Pazos, C. E. Bisaillon, P. Debergue, B. Boulet, and R. Diraddo, "Assessing mechanical properties with intravascular or endoscopic optical coherence tomography," Proc. SPIE, vol. 7897, p. 789708, 2011.

[11] H. Azarnoush, S. Vergnole, M. Hewko, B. Boulet, M. Sowa, and G. Lamouche, "Detection of inflating balloon in optical coherence tomography images of a porcine artery in a beating heart experiment," Proc. SPIE, vol. 7964, p. 79641V, 2011.

 [12] H. Azarnoush, S. Vergnole, M. Hewko, B. Boulet, M. Sowa, and G.
 Lamouche, "Detection of inflating balloon in optical coherence tomography images of a porcine artery in a beating heart experiment," Proc. SPIE, vol. 7964, p. 79641V, 2011. 11] H. Azarnoush, S. Vergnole, M. Hewko, B. Boulet, M. Sowa, and G. Lamouche, "Detection of inflating balloon in optical coherence tomography images of a porcine artery in a beating heart experiment," Proc. SPIE, vol. 7964, p. 79641V, 2011.

 [12] H. Azarnoush, S. Vergnole, M. Hewko, B. Boulet, M. Sowa, and G.
 Lamouche, "Detection of inflating balloon in optical coherence tomography images of a porcine artery in a beating heart experiment," Proc. SPIE, vol. 7964, p. 79641V, 2011.

CAINES, Peter

Articles in refereed publications

M. Nourian, R. P. Malhame', M.Y. Huang, P. E. Caines, "Mean Field (NCE) Formulation of Estimation Based Leader-Follower Collective Dynamics". Frank Lewis Festschrift edition of the International Journal of Robotics and Automation, Special Issue on New Advances in Nonlinear and Optimal Controls of Robotic and Autonomous Systems, Vol. 26, No. 1, 2011, pp. 120-129.

F. Taringoo, P. E. Caines, "Gradient geodesic and Newton geodesic HMP algorithms for the optimization of hybrid systems" (D. Q. Mayne Festschrift edition), Annual Reviews in Control, Volume 35, Issue 2, December 2011, pp.187-198

F. Taringoo and P.E.Caines, ``On the Extension of the Hybrid Maximum Principle to Riemannian Manifolds.'' Proc. 50th IEEE Conference on Decision and Control, 2011, Orlando, FLA. pp 3301-3306

M. Nourian, P. E. Caines, R. P. Malhame', "An Evolution Mean Field Equation System for Initial Mean Consensus Behaviour: A Stability Analysis", Proc. 50th IEEE Conference on Decision and Control (CDC) and European Control Conference, Orlando, Florida, December 2011, pp 5029-5034

M. Nourian, P. E. Caines and R. P. Malhame', `` A Solution to the Consensus Problem Via a Continuum Based Mean Field Control Approach.'' Proc. 50th IEEE Conference on Decision and Control (CDC) and European Control Conference, Orlando, Florida, December 2011, pp 5808-5713

A. C. Kizilkale and P.E. Caines, ``Mean Field (NCE) Stochastic Control: Populations of Major and Egoist-Altruist Agents, '' Proc. 50th IEEE Conference on Decision and Control, Orlando, Florida, December 2011, pp 5547--5552 D. Gromov and P.E. Caines, "Stability of Interconnected Thermodynamic Systems", Proc. 50th IEEE Conference on Decision and Control (CDC) and European Control Conference, Orlando, Florida, December 2011, pp 6730 - 6735

M. Nourian, P. E. Caines, R. P. Malhame', "Mean field analysis of Controlled Cucker-Smale Type Flocking: Linear Analysis and Perturbation Equations", Proc. 18th IFAC World Congress, Milan, Italy, August 2011, pp. 4471-4476.

D. Gromov and P.E.Caines, "Interconnection of Thermodynamic Control Systems." Proc. 18th IFAC World Congress, Milan, Italy, August 2011, pp 6091-6097

F. Taringoo and P.E.Caines, ``Hybrid Optimal Control on Riemannian Manfiolds and Geometric Optimization Algorithms'', Journe'es de l'Optimisation 2009, HEC, Montreal, 2 - 4 May, 2011. Abstracts p. 19.

D. Gromov and P.E.Caines, ``Optimization of Hybrid Thermodynamic Control Systems with Phase Transitions", Journe'es de l'Optimisation 2009, HEC, Montreal, 2 - 4 May, 2011. Abstracts p. 20

A.C. Kizilkale and P.E. Caines, ``Initial Investigations of the Emergence of Coalitions in Mean Field Stochastic Systems," Journe'es de l'Optimisation 2009, HEC, Montreal, 2 - 4 May, 2011. Abstracts p. 25

M. Nourian, P. E. Caines, R. P. Malhame', "An Evolution Mean Field Equation System of the Consensus Problem", Journe'es de l'Optimisation 2009, HEC, Montreal, 2 - 4 May, 2011. Abstracts p. 25

M. Nourian, P. E. Caines, R. P. Malhame', "A Continuum Mean Field Stochastic Control Approach to the Consensus Problem," SIAM Conference on Control& its Application (CT'11), Baltimore, Maryland, July. 2011, Abstract p.35.

A. C. Kizilkale and P.E. Caines, "Mean Field (NCE) Stochastic
Control: Populations of Major and Egoist-Altruist Agents, "Proc.
50th IEEE Conference on Decision and Control, Orlando, Florida,
December 2011, pp 5547--5552

D. Gromov and P.E. Caines, "Stability of Interconnected Thermodynamic Systems", Proc. 50th IEEE Conference on Decision and Control (CDC) and European Control Conference, Orlando, Florida, December 2011, pp 6730 - 6735 M. Nourian, P. E. Caines, R. P. Malhame', "Mean field analysis of Controlled Cucker-Smale Type Flocking: Linear Analysis and Perturbation Equations", Proc. 18th IFAC World Congress, Milan, Italy, August 2011, pp. 4471-4476.

D. Gromov and P.E.Caines, "Interconnection of Thermodynamic Control Systems." Proc. 18th IFAC World Congress, Milan, Italy, August 2011, pp 6091-6097

F. Taringoo and P.E.Caines, ``Hybrid Optimal Control on Riemannian Manfiolds and Geometric Optimization Algorithms'', Journe'es de l'Optimisation 2009, HEC, Montreal, 2 - 4 May, 2011. Abstracts p. 19.

D. Gromov and P.E.Caines, ``Optimization of Hybrid Thermodynamic Control Systems with Phase Transitions", Journe'es de l'Optimisation 2009, HEC, Montreal, 2 - 4 May, 2011. Abstracts p. 20

A.C. Kizilkale and P.E. Caines, ``Initial Investigations of the Emergence of Coalitions in Mean Field Stochastic Systems,'' Journe'es de l'Optimisation 2009, HEC, Montreal, 2 - 4 May, 2011. Abstracts p. 25

M. Nourian, P. E. Caines, R. P. Malhame', "An Evolution Mean Field Equation System of the Consensus Problem", Journe'es de l'Optimisation 2009, HEC, Montreal, 2 - 4 May, 2011. Abstracts p. 25

M. Nourian, P. E. Caines, R. P. Malhame', "A Continuum Mean Field Stochastic Control Approach to the Consensus Problem," SIAM Conference on Control& its Application (CT'11), Baltimore, Maryland, July. 2011, Abstract p.35.

CLARK, James

Articles in refereed publications

Skaff, S. and Clark, J.J., "Spectral Color Constancy using a Maximum Entropy Approach", JOSA A, Vol. 28, Issue 11, pp. 2385-2399 (2011)

Au, C.E. and Clark, J.J., ``Integrating Multiple Views with Virtual Mirrors to Facilitate Scene Understanding'', ACM Transactions on Applied Perception, Volume 8 Issue 4, November 2011

Other refereed contributions

Au, C.E., Ng, V. and Clark, J.J., ``MirrorMap: Augmenting 2D Mobile Maps

with Virtual Mirrors", 2011 Mobile HCI conference

Demirkus, M., Oreshkin, B., Clark, J.J. and Arbel, T., ``Spatial and probabilistic codebook template based head pose estimation from unconstrained environments'', IEEE International Conference on Image Processing (ICIP), Brussels, September 2011

Haji-Abolhassani, A. and Clark, J.J., ``Visual Task Inference Using Hidden Markov Models'', 2011 International Joint Conference on Artificial Intelligence (IJCAI), pp 1678-1683.

Haji-Abolhassani, A. and Clark, J.J., ``Realization of an Inverse Yarbus Process via Hidden Markov Models for Visual-Task Inference'', 2011 Vision Science Symposium (VSS).

COOPERSTOCK, Jeremy

Articles in refereed publications

J. R. Cooperstock. "Multimodal Telepresence Systems: Supporting Demanding Collaborative Human Activities." In: IEEE Signal Processing 28.1 (Jan. 2011), pp. 77–86.

L. To, B. Thompson, J.R. Blum, G. Maehara, R. Hess, and J. R. Cooperstock. "A game platform for treatment of amblyopia." In: IEEE Transactions on Neural Systems and Rehabilitation Engineering 19.3 (June 2011), pp. 280–289. url:

http://ieeexplore.ieee.org/stamp/stamp.jsp?tp=&arnumber=5713843.

S. Pelletier and J. R. Cooperstock. "Preconditioning for Edge-Preserving Image Super- Resolution." In: IEEE Transactions on Image Processing (2011). url:

http://ieeexplore.ieee.org/stamp/stamp.jsp?tp=&arnumber=5898412.

Y. Visell, B.L. Giordano, G. Millet, and J. R. Cooperstock. "Vibration Influences Haptic Perception of Surface Compliance During Walking." In: PLoS ONE 6.3: e17697 (2011). doi:10.1371/journal.pone.0017697. url: http://dx.plos.org/10.1371/journal.pone.0017697.

Z. Qi and J. R. Cooperstock. "Towards Dynamic Image Mosaic Generation With Robustness to Parallax." In: IEEE Transactions on Image Processing (2011). url:

http://ieeexplore.ieee.org/stamp/stamp.jsp?tp=&arnumber=5959979.

D. El-Shimy, F. Grond, A. Olmos, and J. R. Cooperstock. "Eyes-Free Environmental Awareness for Navigation." In: Springer Journal on Multimodal User Interfaces, Special Issue on Interactive Sonification (2011), 11 pages. doi: 10.1007/s12193-011-0065-5. url: http://www.springerlink.com/content/857h542884084ql2/. Other refereed contributions

Papers in refereed conference proceedings:

F. Bérard, G. Wang, and J. R. Cooperstock. "On the Limits of the Human Motor Control Precision: the Search for a Device's Human Resolution." In: INTERACT. Lisbon, Portugal, Sept. 2011, pp. 107–122.

A. Olmos, P. Rushka, D. Ko, G. Foote, W. Woszczyk, and J. R. Cooperstock. "Where do you want your ears? Comparing performance quality as a function of listening position in a virtual jazz band." In: Sound, Music and Computing. July 2011, 6 pgs.

G. Millet, M. Otis, G. Chaw, and J. R. Cooperstock. "Initial Development of a Variable- Friction Floor Surface." In: Canadian Medical and Biological Engineering Conference. Festival of International Conferences on Caregiving, Disability, Aging and Technology, June 2011, 4 pgs.

G. Wang, M. McGuffin, F. Bérard, and J. R. Cooperstock. "Pop-up Depth Views for Improving 3D Target Acquisition." In: Graphics Interface. St. John's, NL, May 2011, pp. 41–48.

I. Garcia-Dorado and J. R. Cooperstock. "Automatic multi-projector calibration with an uncalibrated camera." In: International Workshop on Projector-Camera Systems. Colorado Springs: IEEE, June 2011, pp. 29–36.

J. Blum, H. Sun, A. Olmos, and J. R. Cooperstock. "End-User Viewpoint Control of Live Video from a Medical Camera Array." In: International Conference on Distributed Smart Cameras. Ghent, Belgium, Aug. 2011, pp. 1–6. url: http://www.cim.mcgill.ca/ sre/publications/2011-ICDSC.pdf.

J. Blum, M. Bouchard, and J. R. Cooperstock. "What's around me? Spatialized audio augmented reality for blind users with a smartphone." In: Mobile and Ubiquitous Systems (BEST PAPER AWARD). Published as Lecture Notes of the Institute for Computer Sciences, Social Informatics and Telecommunications Engineering. Springer, Dec. 2011.

J. Ip and J. R. Cooperstock. "To Virtualize or Not? The Importance of Physical and Virtual Components in Augmented Reality Board Games." In: International Conference on Entertainment Computing. Vancouver, BC, Canada: Springer-Verlag, Oct. 2011.

M. Otis, G. Millet, S. Beniak, and J. R. Cooperstock. "Modeling of Lower Limbs for Vibrotactile Compensation." In: Canadian Medical and Biological Engineering Conference. Festival of International Conferences on Caregiving, Disability, Aging and Technology, June 2011, 4 pgs.

N. Bouillot, M. Tomiyoshi, and J. R. Cooperstock. "Extended User Control over Multi-channel Content Delivered over the Web." In: Conference on Audio Networking. San Diego: Audio Engineering Society, Nov. 2011, 5 pgs.

Presentations in refereed conferences

J. R. Cooperstock. "From Rehearsal to Performance: Ensemble Learning in Open Orchestra and Distributed Rehearsal for World Opera" In: Music Anywhere, Anytime: International Symposium on Synchronous Distance Learning. Oct. 2011.

FERRIE, Frank

Articles in refereed publications

Phan, Andrew, and Ferrie, Frank. P., "Interpolating Sparse GPS Measurements Via Relaxation Labeling and Belief Propagation for the Redeployment of Ambulances," IEEE Transactions on Intelligent Transportation Systems, Volume 12, Number 4, December 2011, pp. 1587-1598.

Other refereed contributions

Abou-Moustafa, Karim and Ferrie, Frank P., "A Framework for Hypothesis Learning Over Sets of Vectors," Proc. ACM SIG KDD 9th Workshop on Data Mining and Learning with Graphs, Washington D.C., July 24-25, 2011.

Abou-Moustafa, Karim, Shah, Mohak, De La Torre, Fernando, and Ferrie, Frank P., "Relaxed Exponential Kernels for Unsupervised Learning," Proc. 3rd Annual Symposium of the German Assoc. for Pattern Recognition, Frankfurt, Germany, August 30 to September 2, 2011, pp. 184-195.

Wang, R., and Ferrie, F.P., "Window Detection from Mobile Lidar Data," IEEE Workshop on Applications of Computer Vision (WACV), Kona, Hawaii, January 5-7, 2011, pp. 58-65.

LEVINE, Martin

Visual Saliency Based on Scale-Space Analysis in the Frequency Domain Jian Li, Martin D. Levine, Xiangjing An, Xin Xu, Hangen He IEEE Transactions for Pattern Analysis and Machine Intelligence, in revision, Dec. 15, 2011.

Jian Li (NUDT), Martin Levine (McGill), Xiangjing An (NUDT), Hangen He (NUDT) Saliency Detection Based on Frequency and Spatial Domain Analyses, BMVC 2011, The 22nd British Machine Vision Conference, University of Dundee, 29 August - 2 September 2011

MAHAJAN, Aditya

Articles in refereed publications

A. Nayyar, A. Mahajan, and D. Teneketzis, Optimal control strategies in delayed sharing information structures, IEEE Transactions on Automatic Control, vol. 56, no. 7, pp. 1606-1620, July, 2011.

Other refereed contributions

A. Mahajan, Optimal decentralized control of coupled subsystems with control sharing, in the Proceedings of the 50th IEEE Conference on Decision and Control, Dec 2011.

MICHALSKA, Hannah

Articles in refereed publications

1. Gosline, A., Hayward, V., Michalska, H., "Ineluctability of oscillations in systems with digital implementation of derivative feedback", Automatica, Vol. 47, 2011, pp. 2444-2450 -- (7 pages).

2. Michalska, H., "Generic Nonlinear Stabilization of Systems with Matching Algebraic Structure", Annual Reviews in Control, Vol. 35, 2011, pp. 215-234 -- (20 pages).

Other refereed contributions

3. Hadzagic, M, Michalska, H., "A Bayesian inference approach for batch trajectory estimation", Proceedings of the 14th International Conference on Information Fusion, Print ISBN: 978-1-4577-0267-9; INSPEC Accession Number: 12177654; 5-8 July 2011, Chicago, IL, USA, pp. 1-8.

PUBLICATIONS - Department of Mechanical Engineering

ANGELES, Jorge

Articles in refereed publications

Azimi, A., Hirschkorn, M., Ghotbi, B., Kvecses, J., Angeles, J., Radziszewski, P., Teichmann, M., Courchesne, M., Gonthier, Y., 2011, "Terrain modelling in simulation-based performance evaluation of rovers, " Canadian Aeronautics and Space Journal, Vol. 57, No. 1, pp. 24-33. Figliolini G. and Angeles J., 2011, "Synthesis of the Pitch Cones of N-Lobed Elliptical Bevel Gears," ASME J. Mechanical Design, vol. 133, No. 3, pp. 031002-1-031002-8. Khan, W.A. and Angeles, J., 2011, "A novel paradigm for the qualitative synthesis of simple kinematic chains based on complexity measures," ASME Journal of Mechanisms and Robotics, Vol. 3, No. 3, pp. 031010-1-031010-11.

Carbone, G., Cannella, G. and Angeles, J., 2011, "Derivation of the Mass Matrix for the McGill Schönflies motion generator," Mechanics Based Design of Structures and Machines, Vol. 39(2), pp. 159-178.

Gracia, L. and Angeles, J., 2011, "Robustness to algorithmic singularities and sensitivity in computational kinematics," Proc. IMechE, Part C, J. Mechanical Engineering Science, Vol. 25, No. 4, pp. 987-999.

Al-Widyan, K., Ma, X.Q. and Angeles, J., 2011, "The robust design of parallel spherical robots," Mechanism and Machine Theory Vol. 46, pp. 335-343.

Other refereed contributions

Azimi, A., Kövecses, J. and Angeles, J., 2011, "Wheel-soil interaction model for rover simulation based on plasticity theory," Proc. 2011 IEEE/RSJ International Conference on Intelligent Robots and Systems IROS 2011, Sept. 25-30, San Francisco, CA, pp. 280-285.

Ghotbi, B., Azimi, A., Kövecses, J. and Angeles, J., 2011, "Sensitivity analysis of mobile robots for unstructured environments," Proc. ASME 2011 International Design Engineering Technical Conferences& Computers and Information in Engineering Conference IDETC/CIE 2011, August 28-31, Washington, DC, Paper DETC2011-48440.

Zou, T. and Angeles, J., 2011, "Decoupling of the Cartesian stiness matrix: a case study on accelerometer design," Proc. ASME 2011 International Design Engineering Technical Conferences& Computers and Information in Engineering Conference IDETC/CIE 2011, August 28-31, Washington, DC, Paper DETC2011-47914.

Angeles, F. and Angeles, J., 2011, "Synthesis of function-generating linkages with minimax design error: the linear case," Proc. 13th IFToMM World Comgress, Guanajuato, Gto., Mexico, June 20-22, Paper A_344.

Alizadeh, D., Angeles, J. and Nokleby, S., 2011, "Optimization of a spherical `homokinetic' linkage with minimum design error and maximum transmission quality," Proc. 13th IFToMM World Congress, Guanajuato, Gto., Mexico, June 20-22, Paper A_354.

Barnett, E., Angeles, J., Pasini, D. and Sijpkes, P, 2011, "Surface mapping feedback for robot-assisted rapid prototyping," Proc. IEEE Int. Conf. Robotics and Automation, ICRA 2011, Shanghai, May 9-13, pp. 3739-3744.

McGill Centre for Intelligent Machines (CIM) Annual Report 2011

Angeles, J., 2011, Dynamic Response of Linear Mechanical Systems. Modeling, Analysis and Simulation, Springer, New York, 559 pp.

CORTELEZZI, Luca

Articles in refereed publications

F. Rizzi and L. Cortelezzi, "Stirring, stretching and transport generated by a pair of like-signed vortices", Journal of Fluid Mechanics, vol. 674, pp. 244–280, 2011.

KOVECSES, Jozsef

Articles in refereed publications

J1. Ruzzeh, B., and Kövecses, J.: "A Penalty Formulation for Dynamics Analysis of Redundant Mechanical Systems". ASME Journal of Computational and Nonlinear Dynamics, Vol. 6, 021008, pp. 1-12, 2011.

J2. Meshreki, M., Attia, H. and Kövecses, J.: A New Analytical Formulation for the Dynamics of Multi-Pocket Thin-Walled Structures Considering the Fixture Constraints". ASME Journal of Manufacturing Science and Engineering, Vol. 133, No. 2, 021014, pp. 1-14, 2011.

J3. Kalantari, M., Ramezanifard, M., Dargahi, J. and Kövecses, J.: "3D Graphical Rendering of Localized Lumps and Arteries for Robotic Assisted MIS". ASME Journal of Medical Devices, Vol. 5, No. 2, 021002, pp. 1-10, 2011.

J4. Azimi, A., Hirschkorn, M., Ghotbi, B., Kövecses, J., Angeles, J., Radziszewski, P., Teichmann, M., Courchesne, M., and Gonthier, Y.: "Terrain Modelling in Simulation-based Performance Evaluation of Rovers ". Canadian Aeronautics and Space Journal, Vol. 57, No. 1, pp. 24-33, 2011.

J5. Meshreki, M., Attia, H. and Kövecses, J.: "Development of a New Model for the Varying Dynamics of Flexible Pocket-Structures during Milling". ASME Journal of Manufacturing Science and Engineering, Vol. 133, No. 4, 041002, pp. 1-14, 2011.

J6. Kalantari, M., Ramezanifard, M., Ahmadi, R, Dargahi, J., and
Kövecses, J.: "A Piezoresistive Tactile Sensor for Tissue
Characterization during Catheter-based Cardiac Surgery". International
Journal of Medical Robotics and Computer Assisted Surgery, Vol. 7, No.
4, pp. 431-440, 2011.

Other refereed contributions

Edited Book:

B1. McPhee, J. and Kövecses, J. (Eds.): "IUTAM Symposium on Human Body Dynamics". Elsevier, Procedia, Vol. 2, 2011.

Refereed Conference Papers with Full Oral Presentation:

C1. Mohtat, A., Ghaffari, K. T. and Kövecses, J.: "Recursive State Parameter Estimation of Haptic Robotic Systems". 2011 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Sept. 25-30 2011, San Francisco, CA. (acceptance rate for this conference was 32%)

C2. Azimi, A., Kövecses, J. and Angeles, J.: "Wheel-Soil Interaction Model for Rover Simulation Based on Plasticity Theory". 2011 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Sept. 25-30 2011, San Francisco, CA. (acceptance rate for this conference was 32%)

C3. Shayan Amin, S., Kövecses, J.: "Dynamics of Multibody Haptic Systems", ASME 2011 International Design Engineering Technical Conferences, 8th International Conference on Multibody Systems, Nonlinear Dynamics, and Control, Washington, D.C., August 28-31, 2011.

C4. Kovacs, L.L., Kövecses, J., Zelei, A., Bencsik, L. and Stepan, G.: Servo-Constraint Based Computed Torque Control of Underactuated Mechanical Systems, ASME 2011 International Design Engineering Technical Conferences, 8th International Conference on Multibody Systems, Nonlinear Dynamics, and Control, Washington, D.C., August 28-31, 2011.

C5. Ghotbi, B., Azimi, A., Kövecses, J., Angeles, J.: "Sensitivity Analysis of Mobile Robots for Unstructured Environments", ASME 2011 International Design Engineering Technical Conferences, 8th International Conference on Multibody Systems, Nonlinear Dynamics, and Control, Washington, D.C., August 28-31, 2011.

C6. Gholami, F., Kövecses, J. and Font-Llagunes, J.M.: "Parametric Analysis of Impact Configurations in Crutch Walking." 2011 ECCOMAS Multibody Dynamics Conference, Brussels, Belgium, July 4-7, 2011.

C7. González, F., Kövecses, J., Teichmann, M. and Courchesne, M.: "Techniques for the Simulation of Redundantly Constrained Multibody Systems." 2011 ECCOMAS Multibody Dynamics Conference, Brussels, Belgium, July 4-7, 2011.

C8. Hirschkorn, M., Kövecses, J. and Teichmann, M.: "Dynamics Formulation and Modelling of Wheeled Rovers on Soft Soil." 2011 ECCOMAS Multibody Dynamics Conference, Brussels, Belgium, July 4-7, 2011.

C9. Kövecses, J. and Kovács, L.L.: "Foot Impact in Different Modes of Running: Mechanisms and Energy Transfer." IUTAM Symposium on Human Body Dynamics, Waterloo, ON, Canada, June 5-8, 2011. C10. Ghaffari, K.T., Kövecses, J. and Karam, P.: "Adaptive Frequency Differentiation: An Approach to Increase the Transparency and Performance of Haptic Devices." 2011 IEEE International Conference on Robotics and Automation, Shanghai, China, May 9-13, 2011. (acceptance rate for this conference was 49%)

Refereed Conference Abstracts with Full Oral Presentation:

CA1. Ghaffari, K. T., and Kövecses, J.: "A Velocity Estimator for Increasing the Transparency and Stability of Haptic Devices." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011.

CA2. Shayan Amin, S., Kövecses, J.: "Dynamic Analysis of Force Feedback Devices." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011.

CA3. Mohtat, A., Ghaffari, K.T. and Kövecses, J.: "Unscented Kalman Filtering for Identification of Haptic Robotic Systems." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011.

CA4. Hirschkorn, M., Kövecses, J. and Teichmann, M.: "Dynamics Formulation and Modelling of Wheeled Rovers on Soft Soil." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011.

CA5. Azimi, A., Kövecses, J. and Angeles, J.: "Wheel-soil Interaction Modelling for Dynamics Simulation of Rovers." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011.

CA6. Shen, J.J., Kalantari, M., Kövecses, J., Angeles, J. and Dargahi, J.: "Dynamic Mechanical Analysis Application in Measuring the Viscoelastic Behaviour of Atrial Tissue." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011.

Technical Conferences, 8th International Conference on Multibody Systems, Nonlinear Dynamics, and Control, Washington, D.C., August 28-31, 2011.

C4. Kovacs, L.L., Kövecses, J., Zelei, A., Bencsik, L. and Stepan, G.: Servo-Constraint Based Computed Torque Control of Underactuated Mechanical Systems, ASME 2011 International Design Engineering Technical Conferences, 8th International Conference on Multibody Systems, Nonlinear Dynamics, and Control, Washington, D.C., August 28-31, 2011.

C5. Ghotbi, B., Azimi, A., Kövecses, J., Angeles, J.: "Sensitivity Analysis of Mobile Robots for Unstructured Environments", ASME 2011 International Design Engineering Technical Conferences, 8th International Conference on Multibody Systems, Nonlinear Dynamics, and Control, Washington, D.C., August 28-31, 2011. C6. Gholami, F., Kövecses, J. and Font-Llagunes, J.M.: "Parametric Analysis of Impact Configurations in Crutch Walking." 2011 ECCOMAS Multibody Dynamics Conference, Brussels, Belgium, July 4-7, 2011.

C7. González, F., Kövecses, J., Teichmann, M. and Courchesne, M.: "Techniques for the Simulation of Redundantly Constrained Multibody Systems." 2011 ECCOMAS Multibody Dynamics Conference, Brussels, Belgium, July 4-7, 2011.

C8. Hirschkorn, M., Kövecses, J. and Teichmann, M.: "Dynamics Formulation and Modelling of Wheeled Rovers on Soft Soil." 2011 ECCOMAS Multibody Dynamics Conference, Brussels, Belgium, July 4-7, 2011.

C9. Kövecses, J. and Kovács, L.L.: "Foot Impact in Different Modes of Running: Mechanisms and Energy Transfer." IUTAM Symposium on Human Body Dynamics, Waterloo, ON, Canada, June 5-8, 2011.

C10. Ghaffari, K.T., Kövecses, J. and Karam, P.: "Adaptive Frequency Differentiation: An Approach to Increase the Transparency and Performance of Haptic Devices." 2011 IEEE International Conference on Robotics and Automation, Shanghai, China, May 9-13, 2011. (acceptance rate for this conference was 49%)

Refereed Conference Abstracts with Full Oral Presentation:

CA1. Ghaffari, K. T., and Kövecses, J.: "A Velocity Estimator for Increasing the Transparency and Stability of Haptic Devices." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011.

CA2. Shayan Amin, S., Kövecses, J.: "Dynamic Analysis of Force Feedback Devices." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011.

CA3. Mohtat, A., Ghaffari, K.T. and Kövecses, J.: "Unscented Kalman Filtering for Identification of Haptic Robotic Systems." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011.

CA4. Hirschkorn, M., Kövecses, J. and Teichmann, M.: "Dynamics Formulation and Modelling of Wheeled Rovers on Soft Soil." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011.

CA5. Azimi, A., Kövecses, J. and Angeles, J.: "Wheel-soil Interaction Modelling for Dynamics Simulation of Rovers." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011.

CA6. Shen, J.J., Kalantari, M., Kövecses, J., Angeles, J. and Dargahi, J.: "Dynamic Mechanical Analysis Application in Measuring the Viscoelastic Behaviour of Atrial Tissue." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011. C6. Gholami, F., Kövecses, J. and Font-Llagunes, J.M.: "Parametric Analysis of Impact Configurations in Crutch Walking." 2011 ECCOMAS Multibody Dynamics Conference, Brussels, Belgium, July 4-7, 2011.

C7. González, F., Kövecses, J., Teichmann, M. and Courchesne, M.: "Techniques for the Simulation of Redundantly Constrained Multibody Systems." 2011 ECCOMAS Multibody Dynamics Conference, Brussels, Belgium, July 4-7, 2011.

C8. Hirschkorn, M., Kövecses, J. and Teichmann, M.: "Dynamics Formulation and Modelling of Wheeled Rovers on Soft Soil." 2011 ECCOMAS Multibody Dynamics Conference, Brussels, Belgium, July 4-7, 2011.

C9. Kövecses, J. and Kovács, L.L.: "Foot Impact in Different Modes of Running: Mechanisms and Energy Transfer." IUTAM Symposium on Human Body Dynamics, Waterloo, ON, Canada, June 5-8, 2011.

C10. Ghaffari, K.T., Kövecses, J. and Karam, P.: "Adaptive Frequency Differentiation: An Approach to Increase the Transparency and Performance of Haptic Devices." 2011 IEEE International Conference on Robotics and Automation, Shanghai, China, May 9-13, 2011. (acceptance rate for this conference was 49%)

Refereed Conference Abstracts with Full Oral Presentation:

CA1. Ghaffari, K. T., and Kövecses, J.: "A Velocity Estimator for Increasing the Transparency and Stability of Haptic Devices." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011.

CA2. Shayan Amin, S., Kövecses, J.: "Dynamic Analysis of Force Feedback Devices." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011.

CA3. Mohtat, A., Ghaffari, K.T. and Kövecses, J.: "Unscented Kalman Filtering for Identification of Haptic Robotic Systems." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011.

CA4. Hirschkorn, M., Kövecses, J. and Teichmann, M.: "Dynamics Formulation and Modelling of Wheeled Rovers on Soft Soil." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011.

CA5. Azimi, A., Kövecses, J. and Angeles, J.: "Wheel-soil Interaction Modelling for Dynamics Simulation of Rovers." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011.

CA6. Shen, J.J., Kalantari, M., Kövecses, J., Angeles, J. and Dargahi, J.: "Dynamic Mechanical Analysis Application in Measuring the Viscoelastic Behaviour of Atrial Tissue." 2011 CCToMM Symposium on Mechanisms, Machines, and Mechatronics, Montreal, Quebec, June 2-3, 2011.

NAHON, Meyer

Articles in refereed publications

L. Luo and M. Nahon, 2011, 'Development and Validation of Geometry-Based Compliant Contact Models', ASME Journal of Computational and Nonlinear Dynamics, Vol. 6, No. 1, 11 pages.

Y. Li, M. Nahon and I. Sharf, 2011, 'Airship Dynamics Modeling: A Literature Review', Progress in Aerospace Sciences, Vol. 47, No. 3, pp. 217-239.

A. Saunders and M. Nahon, 2011, 'The Effect of Forward Vehicle Velocity and Drift Angle on Through-Body AUV Tunnel Thruster Performance', Ocean Systems Engineering, Vol 1, No. 4, 19 pages.

Other refereed contributions

T. Liesk and M. Nahon, 2011, 'An Investigation of the Equations of Motion of an Airship in a Wind Field', 7th European Nonlinear Dynamics Conference, July 24-29, Rome, Italy.

J. Wiens and M. Nahon, 2011, 'Modelling and Optimization of Anguilliform Swimming for Robotic Applications', UUST'11, Aug. 22-24, Durham, NH.

SHARF, Inna

Articles in refereed publications

J1. Zarrouk, D., I. Sharf and M. Shoham, "Analysis of Worm-like Robotic Locomotion on Compliant Surfaces," IEEE Transactions on Biomedical Engineering, Vol. 58, No. 2, pp. 301-309, 2011. J2. Li, Y., N. Nahon and I. Sharf, "Airship Dynamics Modeling: A Literature Review," Progress in Aerospace Sciences, Vol. 47, No. 3, pp. 217-239, 2011.

J3. Zhang, Y. and I. Sharf, "Force Reconstruction for Low Velocity Impact Using Force and Acceleration Measurements," Journal of Vibration and Control, Vol. 17, No. 3, pp. 407-420, 2011.

Other refereed contributions

C1. Persson, S. M. and I. Sharf, "Dynamics, Stability and Control of Indoor Spherical Airship," Proc. 7th European Nonlinear Dynamics
Conference, ENOC2011, Rome, Italy, July 24-29, 2011.
C2. Nguyen Huynh, T.-C. and I. Sharf, "Adaptive Reactionless Motion for Space Manipulator when Capturing an Unknown Tumbling Target," Proc. IEEE International Conference on Robotics and Automation, ICRA2011, Shanghai, China, May 9-13, 2011. ECHORD European Community Commission 2. Space Robotics, Unmanned Aerial Vehicles and Legged Robots, Presentation to ECHORD European Community Commission visitors, McGill, 10/2011

PUBLICATIONS- School of Computer Science

DUDEK, Gregory

DUDEK, G. (Giguère, P. and Dudek, G.) A Simple Tactile Probe for Surface Indentification by Mobile Robots, IEEE Transaction on Robotics, 2011, pp. 534-544.

--(Yogesh, G., Xu, A., Dey, B.B., Meghjanim M., Shkurti F., Rekleitis, I., and Dudek,G.) MARE: Marine Autonomous Robotic Explorer, Proceedings of the 2011 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS '11), San Francisco, USA, September 2011, pp. 5048 - 5053, Digital Object Identifier: 10.1109/IROS.2011.6048582.

--(Li, J., Xu, A. and Dudek, G.) Graphical State Space Programming: A Visual Programming Paradigm for Robot Task Specification, 2011 IEEE International Conference on Robotics and Automation (ICRA '11), Shanghai, China, May 2011, pp. 4846-4853.

--(Virie, P. and Dudek, G.) Conformative Filter : A Probabilistic Framework for Localization in Reduced Space, Proceedings of the 8th Canadian Conference on Computer and Robot Vision (CRV '11), St. John's, Newfoundland, Canada, May 2011, pp. 24-31.

--(Shkurti, Florian, Ioannis Rekleitis, and Gregory Dudek) Feature Tracking Evaluation for Pose Estimation in Underwater Environments, Proceedings of the 8th Canadian Conference on Computer and Robot Vision (CRV '11), St. John's, Newfoundland, Canada, May 2011, pp. 160-167.

--(Meghjani,Malika and Gregory Dudek) Combining Multi-Robot Exploration and Rendezvous, Proceedings of the 8th Canadian Conference on Computer and Robot Vision (CRV '11), St. John's, Newfoundland, Canada, May 2011, pp. 80-85.

--(Girdhar,Yogesh and Gregory Dudek) Online Visual Vocabularies, Proceedings of the 8th Canadian Conference on Computer and Robot Vision (CRV '11), St. John's, Newfoundland, Canada, May 2011, pp. 191-196.

--(Yogesh Girdhar and Gregory Dudek) Offline Navigation Summaries, Proceedings of the IEEE International Conference on Robotics and Automation (ICRA2011), Shanghai, China, May 9-13, 2011, pp. 5769-5775. --(Anqi Xu and Gregory Dudek) Fourier Tag: A Smoothly Degradable Fiducial Marker System with Configurable Payload Capacity, Proc. Conference on Computer and Robot Vision (CRV '11), St. John's, Newfoundland, Canada, May 2011, pp. 40-47.

--(Junaed Sattar and Gregory Dudek) Towards Quantitative Modeling of Task Confirmations in Human-Robot Dialog, Proceedings of the IEEE International Conference on Robotics and Automation (ICRA), Shanghai, China, May 9-13, 2011, pp. 1957-1963.

--(Yogesh Girdhar and Gregory Dudek) A surprising problem in navigation, In Vision in 3D Environments, Cambridge University Press, 2011, pp. 228-252. ISBN-13: 9781107001756

LANGER, Michael

LANGER, M. (McCloskey, S., Langer, M., and Siddiqi, K.) Removal of partial occlusion from single images. IEEE Transactions on Pattern Analysis and Machine Intelligence, March 2011, v. 33, no. 3, pp. 647-654.

--(V.Couture, Langer, M., and Roy, S.) Panoramic stereo video textures, IEEE International Conference on Computer Vision (ICCV), Barcelona, Spain. November 2011, pp. 1251-1258.

--(Mannan, F., and Langer, M.) Performance of stereo methods in cluttered scenes. Eighth Canadian Conference on Computer and Robot Vision, St. Johns, NL, May 2011, pp. 94 – 101.

PINEAU, Joelle

PINEAU, J. (S. Ross, J. Pineau, B. Chaib-draa, P. Kreitmann) A Bayesian Approach for Learning and Planning in Partially Observable Markov Decision Processes, Journal of Machine Learning, 12, 2011, pp.1655-1696..

--(M. M. Fard, J. Pineau) Non-Deterministic Policies in Markovian Decision Processes, Journal of Artificial Intelligence Research (JAIR), 2011, 40. pp.1-24.

--(S. M. Shortreed, E. Laber, D. J. Lizotte, S. Stroup, J. Pineau, S. Murphy) Informing sequential clinical decision-making through reinforcement learning: an empirical study, Machine Learning, 2011, 84(1), pp.109-136.

--(J. Pineau, R. West, A. Atrash, J. Villemure, F. Routhier) On the Feasibility of Using a Standardized Test for Evaluating a Speech-Controlled Smart Wheelchair, International Journal of Intelligent Control and Systems, 2011, 16(2), pp.121-128. --(R.D. Vincent, A. Courville, J. Pineau) A bistable computational model of recurring epileptiform activity as observed in rodent slice preparation, Neural Networks, 2011, 24(6), pp.526-537.

--(A. M. S. Barreto, D. Precup, J. Pineau) Reinforcement Learning using Kernel-Based Stochastic Factorization, Neural Information Processing Systems (NIPS-24), 2011.

--(M. Fard, J. Pineau, C. Szepesvari) PAC-Bayesian Policy Evaluation for Reinforcement Learning, Proceedings of the Conference on Uncertainty in Artificial Intelligence (UAI), 2011.

--(K. Deng, J. Pineau and S.A. Murphy) Active Learning for Developing Personalizing Treatment, Proceedings of the Conference on Uncertainty in Artificial Intelligence (UAI), 2011.

--(S. Png, J. Pineau) Bayesian Reinforcement Learning for POMDP-based dialogue systems, International Conference on Acoustics, Speech and Signal Processing (ICASSP), 2011.

--(A. K. Moghaddam, J. Pineau, J. Frank, P. S. Archambault, F. Routhier, T. Audet, J. Polgar, F. Michaud, P. Boissy) Mobility Profile and Wheelchair Driving Skills of Powered Wheelchair Users: Sensor-Based Event Recognition Using a Support Vector Machine Classifier, 33rd Annual International IEEE EMBS Conference, 2011.

--(S.C.W. Ong, Y. Grinberg, J. Pineau) Goal-directed online learning of predictive models, European Workshop on Reinforcement Learning (EWRL), LNCS, Springer, 2011.

--(C. Paduraru, D. Precup, J. Pineau) A framework for computing bounds for the return of a policy, European Workshop on Reinforcement Learning (EWRL), LNCS, Springer, 2011.

--(K. Deng, J. Pineau, S. Murphy) Active Learning for Personalizing Treatment, IEEE Symposium on Adaptive Dynamic Programming and Reinforcement Learning (ADPRL), 2011.

SIDDIQI, Kaleem

SIDDIQI, K. (McCloskey, S., Langer, M., and Siddiqi, K) Removal of partial occlusion from single images, IEEE Transactions on Pattern Analysis and Machine Intelligence, March 2011, v. 33, no. 3, pp. 647-654.

--(Stolpner, S., Whitesides, S., and Siddiqi, K.) Sampled medial loci for 3d shape representation, Computer Vision and Image Understanding, 2011, v. 115, pp. 695-706.

--(Assemlal, H.-E., Tschumperlé, D., Brun, L., and Siddiqi, K.) Recent

advances in diffusion mri modelling: Angular and radial reconstruction, Medical Image Analysis, 2011, v. 15, n. 4, pp. 369-396.

--(Piuze, E., Kry, P., and Siddiqi, K.) Generalized helicoids for modeling hair geometry, Computer Graphics Forum (Proceedings of Eurographics 2011), April 2011, v. 30, n. 2, pp. 247-256.

--(Macrini, D., Dickinson, S., Fleet, D., and Siddiqi, K.) Object categorization using bone graphs, Computer Vision and Image Understanding, 2011, v. 15, pp. 1187-1206.

--(Macrini, D., Dickinson, S., Fleet, D., and Siddiqi, K.) Bone graphs: Medial shape parsing and abstraction, Computer Vision and Image Understanding, 2011, v. 15, pp. 1044-1061.

--(Boucher, M., Evans, A., and Siddiqi, K.) Anisotropic diffusion of tensor fields for fold shape analysis on surfaces, In Proceedings of the Information Processing in Medical Imaging Conference, July 2011, v. 22, pp. 271-282.

--(Stolpner, S., Siddiqi, K., and Whitesides, S.) Approximating the medial axis by shooting rays: 3d case, In Canadian Conference On Computational Geometry, 2011.

--(Assemlal, H.-E., Campbell, J., Pike, B., and Siddiqi, K.) Apparent intravoxel fibre population dispersion (fpd) using spherical harmonics, In International Conference On Medical Image Computing and Computer Assisted Intervention (MICCAI), 2011, pp. 157-165.

--(Campbell, J., MamayyezSiahkal, P., Savadjiev, P., Leppert, I., Siddiqi, K., and Pike, B.) A new comprehensive framework for probabilistic tractography of fanning fibres, In International Society for Magnetic Resonance in Medicine Conference, May 2011. All departments submit an annual report to the university that contains updated information on grants and publications. Please see links below for CIM members and associates.

FACULTY OF SCIENCE

School of Computer Science

http://www.cs.mcgill.ca/research/publications http://www.cs.mcgill.ca/about/reports Full Members: Gregory Dudek, Michael Langer, Joelle Pineau, Kaleem Siddiqi Associate Members: Paul Kry, Xue Liu, Prakash Panangaden, Doina Precup

FACULTY OF MEDICINE

Associate Members:

Dr. Renzo Cecere	http://ct-surgery.mcgill.ca/faculty_rcecere.htm
Dr. Louis Collins	http://www.bic.mni.mcgill.ca/PeopleFaculty/CollinsDLouis
Dr. Bruce Pike	http://www.bic.mni.mcgill.ca/PeopleFaculty/PikeBruce

FACULTY OF ENGINEERING

Department of Electrical and Computer Engineering

http://www.mcgill.ca/ece/about/reports/

Full Members:

Tal Arbel, Benoit Boulet, Peter Caines, James Clark, Jeremy Cooperstock, Frank Ferrie, Martin Levine, Hannah Michalska, Aditya Mahajan

Associate Member:

Sam Musallam

Department of Mechanical Engineering

http://www.mcgill.ca/mecheng

Full Members:

Jorge Angeles, Luca Cortelezzi, Jozsef Kovecses, Meyer Nahon, Inna Sharf, Paul Zsombor-Murray

Associate Members:

Arun Misra, Rosaire Mongrain, James Richard Forbes