

CENTRE FOR INTELLIGENT MACHINES (CIM)

Centre de recherche sur les machines intelligentes

www.cim.mcgill.ca

Annual Report 2012

Draft

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SUMMARY	3
Section I – MEMBERSHIP	
Section II – FUNDING INITIATIVES and AWARDS	7
Section II – PUBLICATIONS	8

SUMMARY

The McGill Centre for Intelligent Machines (CIM) is a multi-disciplinary, inter-departmental, inter-faculty research group formed in 1985 to provide an enriched mentoring and training environment for graduate students studying in the field of robotics and intelligent systems.

For almost 3 decades, CIM has been a pioneering force in cross-disciplinary research. The Centre is primarily located in contiguous space where labs and student offices are shared. CIM's membership and students have been universally recognized over the years for their highest standards of excellence - exceptional scientific achievements and outstanding contributions to society and industry.

CIM's management design and organizational structure have been studied, emulated and adopted by various units, both within the university and outside of McGill, notably in the academic sector. CIM continues to be regarded by its peers as a model for "best practices" in a world now heavily populated by research organizations.

The Centre celebrated its 25th Anniversary with an international guest speaker series and a scientific symposium.

For the year 2012:

The Centre was comprised of 19 members from both the Faculties of Engineering and Science --the Department of Electrical and Computer Engineering, Department of Mechanical Engineering and the School of Computer Science. CIM also has 13 associate members representing a diversity of research collaborations, such as within the Faculty of Medicine -- the Royal Victoria Hospital and the Montreal Neurological Institute.

The Centre was home to a diverse population of about 160 **graduate students, post-docs, research assistants and associates, as well as visiting scholars and undergraduate students from various disciplines.

PhD	Master's	U/Grads	Post-	
			Docs	
69.5	48.5	16	7	145

The CIM members were collaborators and co-collaborators in grants and contracts totally about \$550M.

REPARTI - Regroupement pour l'étude des environnements partagés intelligents répartis

http://reparti.gel.ulaval.ca/en/REPARTI/index.chtml

Centre REPARTI is a \$2.4M inter-institutional, interdisciplinary collaborative venture comprised of 8 Quebec institutions, 33 members and over 200 students. The McGill node of REPARTI is represented by 14 members from the McGill Centre for Intelligent Machines (CIM). The members of the McGill node collaborate in grants and contracts valued in excess of \$5M.

The institutions participating in REPARTI are - Université Laval (host institution), McGill University, Université de Sherbrooke, Ēcole Polytechnique, Université de Montréal, Université du Québec à Chicoutimi and École de technologie supérieure (ÉTS).

Supported by the Quebec government's *Fonds de recherche Nature et technologies (FRNT*), this regroupement stratégique builds on some unique precedents:

- (1) The historical and concrete partnership that developed over the past 25 years between prominent researchers in U. Laval and McGill (CIM) as a result of the NSERC National Centres of Excellence program, the interuniversity-industrial consortium IRIS-Precarn, and the FQRNT Réseau QERRAnet.
- (2) The long and productive relationship established between the McGill Centre for Intelligent Machines (CIM) and the Quebec government through the former FCAR Centre de recherche programme.

The formal renewal process for REPARTI began in the year 2012, and results of the competition will be announced in April 2013.

NEW MEMBER

**Professor Paul Kry became a member of CIM in 2012

CIM welcomed Professor Paul Kry as a full member in 2012. His research interests include computer graphics, physically based animation, skin deformations of articulated characters, motion capture, interaction, and physically based modeling of humans and animals. He is specifically interested in human and animal motor control (e.g., locomotion, grasping, manipulation) in combination with natural phenomena such as the physics of rigid objects, deformation, and contact. Some areas of application in his work include computer animation for video games and movies, training simulations, ergonomics, and biologically inspired robotics and programming by demonstration. An important aspect Prof. Kry's work is the combination of real world measurements, approximate models, and physically based simulation. His research interests expand to machine learning, numerical methods, and audio.

A native of Ottawa, Prof. Kry moved to Waterloo in 1992 to attend the University of Waterloo where he obtained a B.Math. in computer science with electrical engineering electives (1997). His undergraduate studies included a one year exchange to Compiègne, France which included a six month work term in Paris. Upon graduation, he worked for Televitesse (now known as March Networks) before moving to Vancouver for graduate studies at the University of British Columbia. There, he obtained a M.Sc. (2000) and Ph.D. (2005) in computer science with his supervisor Dinesh K. Pai. While studying as a PhD in UBC, he followed Prof. Pai to New Jersey in 2002 to complete his research program at Rutgers University. After finishing he moved directly to Grenoble for postdoctoral work with the EVASION group at INRIA Rhône Alpes and the LNRS at Université René Descartes. Prof. Kry arrived at McGill University as an Assistant Professor in January 2008.

Section I - MEMBERSHIP

FULL MEMBERS

Name	Title	Department	Office	Phone	Email
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		Engineering		398-6315	
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ASSOCIATE MEMBERS

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		Engineering			
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	Professor		326	398-6443	

Section II – FUNDING INITIATIVES AND AWARDS

The Centre's history is rich in scientific reputation and credibility. As a result, several of CIM's members were successful in obtaining major infrastructure grants in 2012, all of which are housed at CIM.

*NSERC Collaborative Research and Training Experience - Medical Imaging Analysis (CREATE-MIA)
The CREATE -MIA received \$1.6M from NSERC and is headed by CIM-REPARTI member Kaleem Siddiqi.
It also includes CIM-REPARTI member Tal Arbel, CIM associate members Bruce Pike and Louis Collins and
REPARTI members Catherine Laporte (ETS) and Maxime Descoteaux (USherbrooke), and others in Quebec.
More information on the CREATE-MIA can be found at http://aggie.cim.mcgill.ca.:8080/create-mia/

* NSERC Automotive Partnership Canada Initiative (APC)

The APC initiative received \$5M from NSERC and is headed by CIM-REPARTI member Benoit Boulet. It also includes CIM-REPARTI members Jorge Angeles and Peter Caines, as well as other researchers at McGill. More information on the APC can be found at http://www.mcgill.ca/channels/news/mcgill-researchers-help-make-electric-cars-cheaper-225179

*NSERC Canadian Field Trial Network - (NCFRN)

The NCFRN received an award of \$5M from NSERC and is headed by CIM-REPARTI member Gregory Dudek. It also includes CIM-REPARTI member Joelle Pineau and CIM member Inna Sharf, and others across Canada. For more information on the NCFRN, please go to: http://ncfrn.mcgill.ca/

AWARDS

Our sincere congratulations go out to all of our CIM student award recipients! The examples below represent only a very small sample of the total number of awards received by our students in 2012.

- *CIM-REPARTI member Jeremy Cooperstock and his team in the Shared Reality Lab won the Mozilla/National Science Foundation Gold Prize "Ignite Challenge" (out of 305 submissions in the Brainstorming Round) for ``Real-Time Emergency Response Observation and Supervision' Canadian Internet Registry Association .CA Impact Award (Applications category) for In-Situ Audio Services Project
- *Amin Haji-Abolhassani, PhD candidate under the supervisor of CIM-REPARTI member Jim Clark, won the Best Student Paper Award at the 2012 Conference on Computer and Robot Vision: Haji-Abolhassani, A. and Clark, J.J., "Information Fusion in Visual Task Inference" 2012, 9th Conference on Computer and Robot Vision (CRV), Toronto, May 2012
- *CIM-REPARTI PhD candidates **Toufic Azar** (ME-Jorge Angeles/Jozsef Kovecses) and **Ahmad Haidar** (ECE-Benoit Boulet) were each a recipient of a **William and Rhea Seath Awards in Engineering Innovation in 2012**. Both Toufic and Ahmad were awarded a stipend of \$20K to be spent on the development of algorithms, fabrication costs and salaries for each of their projects.
- *CIM-REPARTI PhD candidate **Z. Karimaghaloo** (ECE-Tal Arbel) won **Best Paper Award for paper presented at conference STACOM**: Z. Karimaghaloo*, H. Rivaz and T. Arbel, "Hierarchical Conditional Random Fields for Myocardium Infarction Detection", in Proceedings of the Workshop on Statistical Atlases and Computational Models of the Heart (STACOM 2012): DE-MRI Segmentation Challenge held in conjunction with the 15th International Conference on Medical Image Computing and Computer Assisted Intervention (MICCAI '12), Nice, France, October 2012.

Section II - PUBLICATIONS

PUBLICATIONS - Department of Electrical and Computer Engineering

ARBEL, Tal

Articles in refereed publications

- D. De Nigris*, D.L. Collins, and T. Arbel, "Multi-Modal Image Registration based on Gradient Orientations of Minimal Uncertainty", IEEE Transactions on Medical Imaging, Vol. 31, No. 12, pp. 2343-2354, Dec. 2012.
- Z. Karimaghaloo*, M. Shah*, S. Francis, D. L. Arnold, D. L. Collins, and T. Arbel, "Automatic Detection of Gadoliniumenhancing Multiple Sclerosis Lesions in Brain MRI Using Conditional Random Fields", IEEE Transactions on Medical Imaging, Vol. 31, No. 6, pp. 1181-1194, June 2012.

Papers in Refereed Conference Proceedings

- Z. Karimaghaloo*, D. L. Arnold, D. L. Collins and T. Arbel, "Hierarchical Conditional Random Fields for Detection of Gadenhancing Lesions in Multiple Sclerosis", in Proceedings of the 15th International Conference on Medical Image Computing and Computer Assisted Intervention (MICCAI '12), Nice, France, October 2012.
- Z. Karimaghaloo*, H. Rivaz and T. Arbel, "Hierarchical Conditional Random Fields for Myocardium Infarction Detection", in Proceedings of the Workshop on Statistical Atlases and Computational Models of the Heart (STACOM 2012): DE-MRI Segmentation Challenge held in conjunction with the 15th International Conference on Medical Image Computing and Computer Assisted Intervention (MICCAI '12), Nice, France, October 2012. BEST PAPER AWARD (oral presentation)
- N. Subbanna*, V. S. Fonov, D. L. Collins and T. Arbel, "Probabilistic Gabor and Markov Random Fields Segmentation of Brain Tumours in MRI Volumes", in Proceedings of the Workshop on Multimodal Brain Tumor Segmentation Challenge (BraTS 2012) held in conjunction with the 15th International Conference on Medical Image Computing and Computer Assisted Intervention (MICCAI '12), Nice, France, October 2012. (oral presentation)
- B. Oreshkin* and T. Arbel, "Optimization over Random and Gradient Probabilistic Pixel Sampling for Fast, Robust Multi-Resolution Image Registration", in the Fifth Workshop on Biomedical Image Registration (WBIR 2012), Vanderbilt University, Nashville, Tennessee, USA, July 2012. (oral presentation).
- M. Demirkus*, D. Precup, J. Clark, and T. Arbel, "Soft Biometric Trait Classification from Real-world Face Videos Conditioned on Head Pose Estimation", in Proceedings of the IEEE Computer Society Workshop on Biometrics in association with the 2012 IEEE Computer Society Conference on Computer Vision and Pattern Recognition, Providence, Rhode Island, June 2012. (oral presentation)
- D. De Nigris*, D. L. Collins and T. Arbel, "Fast and Robust Registration based on Gradient Orientations: Case Study Matching Intra-operative Ultrasound to Pre-operative MRI in Neurosurgery", In Proceedings of the 3rd International Conference on Information Processing in Computer-Assisted Interventions (IPCAI 2012), Pisa, Italy, June 2012.

Presentation by D. De Nigris*, PhD student under my supervision, "Fast and Robust Registration based on Gradient Orientations: Case Study Matching Intra-operative Ultrasound to Pre-operative MRI in

Neurosurgery", at the 3rd International Conference on Information Processing in Computer-Assisted Interventions (IPCAI 2012), Pisa, Italy, June 2012.

BOULET, Benoit

Articles in refereed publications

- [1] Haidar A, Legault, L., Dallaire, M., Alkhateeb, A., Coriati, A., Messier, V., Cheng, P., Millette, M., Boulet, B., Rabasa-Lhoret, R., "Glucose-responsive Insulin and Glucagon Delivery to Regulate Glucose Levels in Adults with Type 1 Diabetes: Randomized Crossover Controlled Trial" Canadian Journal of Diabetes, October 2012, Vol. 36, Issue 5, Page S16.
- [2] H. Azarnoush, S. Vergnole, V. Pazos, C.-E. Bisaillon, B. Boulet and G. Lamouche, "Intravascular optical coherence tomography to characterize tissue deformation during angioplasty: preliminary experiments with artery phantoms" SPIE Journal of Biomedical Optics, Sept. 2012, Vol. 17, No. 9, 096015.
- [3] H. Azarnoush, S. Vergnole, B. Boulet, M. Sowa and G. Lamouche, "Real-time control of angioplasty balloon inflation based on feedback from intravascular optical coherence tomography: experimental validation on an excised heart and a beating heart model" IEEE Transactions on Biomedical Engineering, May 2012, Vol. 59, No. 5:1488-95.
- [4] Haidar A, Potocka E, Boulet B, Umpleby AM, Hovorka R., Estimating postprandial glucose fluxes using hierarchical Bayes modelling, Comput Methods Programs Biomed. 2012, Vol. 108, No. 1, 10.1016/j.cmpb.2012.01.010
- [5] H. Azarnoush, S. Vergnole, B. Boulet, R. DiRaddo and G. Lamouche, "Real-time Control of Angioplasty Balloon Inflation Based on Feedback from Intravascular Optical Coherence Tomography: Preliminary Study on an Artery Phantom," IEEE Transactions on Biomedical Engineering, March 2012, 59(3):697-705. (previously reported in 2011 report as Epub 2011 Dec. 5)

Other refereed contributions

- [6] O. Alkefer and B. Boulet, "Magnesium Twin Roll Casting Machine: Modeling and Control" 9th Int. Conf. on Magnesium Alloys and their Applications, July 8-12, 2012, Vancouver, Canada.
- [7] M. M. I. Chy and B. Boulet, "Iterative Learning Model Predictive Controller of Plastic Sheet Temperature for a Thermoforming Process" American Control Conference, June 27-29, 2012, Montréal, Québec, pp. 627-633.
- [8] T. Liesk, M. Nahon and B. Boulet, "Design and experimental validation of a controller suite for an autonomous, finless airship" American Control Conference, June 27-29, 2012, Montréal, Québec, pp. 2491-2496.
- [9] R. Modirnia and B. Boulet, "Application of the Watanabe-Modified Smith Predictor Control Technique in Thermoforming" American Control Conference, June 27-29, 2012, Montréal, Québec, pp. 6448-6454.
- [10] C. Zhang, B. Boulet, Z. Heng "Study of soft-sensing technique for temperature distribution during polymer sheet heating process" 24th Chinese Control and Decision Conference, May 23-25, 2012, pp. 194-197.

CAINES, Peter

Articles in refereed publications Publications in Journals and Books

S. Ng and P.E.Caines, "On the Continuity of Optimal Controls and Value Functions with Respect to Initial Conditions," Systems and Control Letters, Vol. 61, December, 2012, pp. 1294-1298

M. Nourian, P. E. Caines, R. P. Malhame, M.Y. Huang, "Mean Field Control in Leader-Follower Stochastic Multi-Agent Systems: Likelihood Ratio Based Adaptation." IEEE Trans. on Automatic Control, Vol. 57, no. 11, Nov. 2012, pp. 2801-2816.

M.Y. Huang, P.E. Caines and R.P. Malhame, "Social Optima in Mean Field LQG Control: Centralized and Decentralized Strategies." IEEE Trans. on Automatic Control, Vol. 57, No. 7, July, 2012, pp. 1736 - 1752

Conference Publications

F. Taringoo and P.E.Caines, ``Newton-Geodesic HMP Algorithms for the Optimization of Hybrid Systems and Geometric Properties of Hybrid Value Functions'', IEEE Conference on Decision and Control, Maui, HI, USA, December, 2012, pp 4211 - 4216

A. C. Kizilkale and P.E. Caines, ``Emergence of Coalitions in Mean Field Stochastic Systems'', IEEE Conference on Decision and Control, Maui, HI, USA, December, 2012, pp. 5768 - 5773

A. C. Kizilkale, S. Mannor and P.E. Caines, "Large Scale Real-Time Bidding in the Smart Grid: A Mean Field Framework ``, IEEE Conference on Decision and Control, Maui, HI, USA, December, 2012, pp.3680 - 3687

M. Nourian and P. E. Caines, ``epsilon-Nash Mean Field Theory for Nonlinear Stochastic Dynamic Games with Major-Minor Agents", IEEE Conference on Decision and Control, Maui, HI, USA, December, 2012, pp. 2090 - 2095

M. Nourian and P. E. Caines, "Nash Mean Field Theory for Nonlinear Stochastic Dynamic Games with Major-Minor Agents", MTNS, Melbourne, July, 2012, Session SE-17. Full paper in: CDROM ISBN: 978-0-646-58062-3 and at www.mtns2012.conference.net.au

A. C. Kizilkale and P.E. Caines, ``Coalition Formation in Mean Field Stochastic Systems'', MTNS, Melbourne, July, 2012, Session SE-17. Full paper in: CDROM ISBN: 978-0-646-58062-3 and at www.mtns2012.conference.net.au

- D. Gromov and P.E. Caines, ``On the Stability of Interconnected Thermodynamic Systems with Heat and Work Exchange '',Proc. 2012 American Control Conference, Montreal, QC, June, 2012, pp. 386 391
- F. Taringoo and P.E.Caines, ``On an Extension of the Hybrid Minimum Principle to Systems on Lie Groups", Proc. 2012 American Control Conference, Montreal, QC, June, 2012, pp 4534 4539
- D. Gromov and P.E. Caines, "Hybrid Thermodynamic Control Systems with Phase Transitions", ADHS12, Eindhoven, Netherlands, June, 2012, pp 277 283

- F. Taringoo and P.E.Caines, `` The Exponential Gradient HMP Algorithm for the Optimization of Hybrid Systems on Lie Groups'', ADHS12, Eindhoven, Netherlands, June, 2012, pp 33 38
- F. Taringoo and P.E.Caines, ``Newton-Geodesic HMP Algorithms for the Optimization of Hybrid Systems and Geometric Properties of Hybrid Value Functions'', IEEE Conference on Decision and Control, Maui, HI, USA, December, 2012, pp 4211 4216
- A. C. Kizilkale and P.E. Caines, "Emergence of Coalitions in Mean Field Stochastic Systems", IEEE Conference on Decision and Control, Maui, HI, USA, December, 2012, pp. 5768 5773
- A. C. Kizilkale, S. Mannor and P.E. Caines, "Large Scale Real-Time Bidding in the Smart Grid: A Mean Field Framework ``, IEEE Conference on Decision and Control, Maui, HI, USA, December, 2012, pp.3680 3687
- M. Nourian and P. E. Caines, ``epsilon-Nash Mean Field Theory for Nonlinear Stochastic Dynamic Games with Major-Minor Agents'', IEEE Conference on Decision and Control, Maui, HI, USA, December, 2012, pp. 2090 2095
- M. Nourian and P. E. Caines, ``Nash Mean Field Theory for Nonlinear Stochastic Dynamic Games with Major-Minor Agents", MTNS, Melbourne, July, 2012, Session SE-17. Full paper in: CDROM ISBN: 978-0-646-58062-3 and at www.mtns2012.conference.net.au
- A. C. Kizilkale and P.E. Caines, ``Coalition Formation in Mean Field Stochastic Systems'', MTNS, Melbourne, July, 2012, Session SE-17. Full paper in:
- CDROM ISBN: 978-0-646-58062-3 and at www.mtns2012.conference.net.au
- D. Gromov and P.E. Caines, "On the Stability of Interconnected Thermodynamic Systems with Heat and Work Exchange ", Proc. 2012 American Control Conference, Montreal, QC, June, 2012, pp. 386 391
- F. Taringoo and P.E.Caines, ``On an Extension of the Hybrid Minimum Principle to Systems on Lie Groups'', Proc. 2012 American Control Conference, Montreal, QC, June, 2012, pp 4534 4539
- D. Gromov and P.E. Caines, ``Hybrid Thermodynamic Control Systems with Phase Transitions'', ADHS12, Eindhoven, Netherlands, June, 2012, pp 277 283
- F. Taringoo and P.E.Caines, `` The Exponential Gradient HMP Algorithm for the Optimization of Hybrid Systems on Lie Groups'', ADHS12, Eindhoven, Netherlands, June, 2012, pp 33 38

CLARK, James

Articles in refereed publications

Ziat, M., Au, C.E., Haji-Abolhassani, A. and Clark, J.J., "Enhancing visuospatial map learning through action on cellphones", ACM Transactions on Applied Perception, Vol. 9, No. 1, March 2012

Other refereed contributions

Demirkus, M., Precup, D., Clark, J.J. and Arbel, T., ``Soft Biometric Trait Classification from Real-world Face Videos Conditioned on Head Pose Estimation.", 2012 CVPR Workshop on Biometrics.

Haji-Abolhassani, A. and Clark, J.J., "Visual Task Inference in Conjunction Search Using Hidden Markov Models and Token Passing", 2012 Vision Science Symposium (VSS), May 2012

Haji-Abolhassani, A. and Clark, J.J., ``Information Fusion in Visual Task Inference'', 2012 9th Conference on Computer and Robot Vision (CRV), May 2012

COOPERSTOCK, Jeremy

Articles in refereed publications

- 1. J. M. Black, R. F. Hess, J. R. Cooperstock, L. To*, and B. Thompson. "The measurement and treatment of suppression in amblyopia." Visualized Experiments e3927 (2012). doi: 10.3791/3927.
- 2. B. L. Giordano, Y. Visell*, H.-Y. Yao, V. Hayward, J. R. Cooperstock, and S. McAdams. "Identification of walked-upon materials in auditory, kinesthetic, haptic and audio-haptic conditions." Acoustical Society of America 131.5
- 3. R. F. Hess, B. Thompson, J. M. Black, G. Maehara, P. Zhang, W. R. Bobier, L. To*, and J. R. Cooperstock. An iPod for treating amblyopia: a pilot study." Optometry
- 4. A. Olmos*, N. Bouillot*, T. Knight*, N. Mabire*, and J. R. Cooperstock. "A High-Fidelity Orchestra Simulator for Individual Musicians' Practice." Computer Music Journal 36.2, pp. 55–73. url: http://www.mitpressjournals.org/doi/pdf/ 10.1162/COMJ_a_00119.
- 5. D. El-Shimy*, F. Grond*, A. Olmos*, and J. R. Cooperstock. "Eyes-Free Environmental Awareness for Navigation." Springer Journal on Multimodal User Interfaces, Special Issue on Interactive Sonification 5.3-4, pp. 131–141. doi: 10.1007/s12193-011-0065-5. url: http://www.springerlink.com/content/857h542884084ql2/.
- G. Cirio*, M. Marchal, A. Lécuyer, and J. R. Cooperstock. "Vibrotactile Rendering of Splashing Fluids." Transactions on Haptics, url: http://ieeexplore.ieee.org/xpls/abs_all.jsp?arnumber=6226398.
- 7. J. Blum*, M. Bouchard*, and J. R. Cooperstock. "Spatialized audio environmental awareness for blind users with a smartphone." Mobile Networks and Applications
- 8. S. Pelletier* and J. R. Cooperstock. "Real-time free viewpoint video from a range sensor and color cameras." Machine Vision and Applications. url: http://www.springerlink.com/content/b53j468736j34060/?MUD=MP.
- 9. Z. Qi* and J. R. Cooperstock. "Toward Dynamic Image Mosaic Generation With Robustness to Parallax." IEEE Transactions on Image Processing 21.1, pp. 366–378. url: http://ieeexplore.ieee.org/stamp/stamp.jsp?tp=&arnumber=5959979.
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Other refereed contributions

Papers in refereed conference proceedings:

- 1. K. Kim, J. Bolton, A. Girouard, J.R. Cooperstock, and R. Vertegaal. "TeleHuman: Effects of 3D Perspective on Gaze and Pose Estimation with a Life-size Cylindrical Telepresence Pod." Human Factors in Computing Systems (CHI). Austin, Texas: ACM Press/Addison-Wesley Publishing Co., May, pp. 2531–2540.
- 2. D. El-Shimy*, T. Hermann, and J. R. Cooperstock. "A Reactive Environment for Dynamic Volume Control." New Interfaces for Musical Expression (NIME). Ann Arbor, Michigan, May, 7 pgs.
- 3. J. Blum*, D. Greencorn*, and J. R. Cooperstock. "Smartphone sensor reliability for augmented reality applications." Mobile and Ubiquitous Systems (Mobiquitous). Beijing, China: Springer, December, 13 pgs.
- 4. T. Knight*, N. Bouillot*, and J. R. Cooperstock. "Visualization feedback for musical ensemble practice: A case study on phrase articulation and dynamics." Visualization and Data Analysis. IS&T/SPIE Symposium on Electronic Imaging, January, 9 pgs.

Book Chapters

- 1. M. Wozniewski, Z. Settel, and J. R. Cooperstock. "Sonic Interaction via Spatial Arrangement in Mixed Reality Environments." In: Sonic Interaction Design, Ed. by K. Franinovic and S. Serafin. MIT Press.
- 2. Y. Visell, R. Rajalingham*, and J. R. Cooperstock. "A review of nonvisual signatures of human walking with applications to person tracking in augmented environments." In: Walking with the senses: Perceptual techniques for walking in virtual environments. Ed. by Y. Visell and F. Fontana. Logos Verlag.
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FERRIE, Frank

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Wang, R., Bach, J., Macfarlane, J., and Ferrie, F.P., A New Upsampling Method for Mobile LiDAR Data, Proc. IEEE Workshop on the Applications of Computer Vision, Jan. 9-11, 2012, Breckenridge, CO., pp. 17-24.

LEVINE, Martin

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- 1. M. Elhamod and Martin D. Levine, "Automated Real-Time Detection of Suspicious Behavior in Public Transport Areas," IEEE Transactions on Intelligent Transportation Systems, 2012 [Accepted for Publication]. (New SCI Impact Factor (IF) is 3.452, ranking number 12 among all IEEE Publications, up from 2.234 and number 36 last year.)
- 2. Jian Li, Martin D. Levine (Student thesis supervisor and primary contributor), Xiangjing An, Xin Xu and Hangen He, Visual Saliency Based on Scale-Space Analysis in the Frequency Domain, IEEE Transactions on Pattern Analysis and Machine Intelligence, 2012 [in Press]

Conference Proceedings

- 1. Mehrsan Javan Roshtkhari & Martin D. Levine, A Multi-Scale Hierarchical Codebook Method for Human Action Recognition in Videos Using a Single Example, presented at the Ninth Conference on Computer and Robot Vision (CRV 2012), Toronto, ON, Canada, 2012.
- 2. M. Elhamod and M. D. Levine, A Real Time Semantics-Based Detection of Suspicious Activities in Public Scenes, Ninth Conference on Computer and Robot Vision, Toronto, 2012

MAHAJAN, Aditya

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Mahajan and S. Tatikonda, "Opportunistic capacity and error exponent region for the compound channel with feedback," IEEE Transactions on Information Theory, vol. 58, pp. 4331-4341, July, 2012.

Other refereed contributions

A. Mahajan, N. Martins, M. Rotkowitz, and S. Yuksel, "Information structures in optimal decentralized control", Proceedings of the 51th IEEE Conference on Decision and Control (CDC), Maui, Hawaii, Dec 10-13, 2011. (Invited tutorial)

A. Mahajan, "Structure of optimal policies in active sensing", Proceedings of the 37th IEEE International Conference on Acoustics, Speech, and Signal Processing (ICASSP), Kyoto, Japan, March 25-30, 2012. (invited)

A. Mahajan, "On optimal block-Markov coding schemes for multiple-access channel with feedback", Conference on Information Science and Systems, Princeton, NJ, March 21-23, 2012. (invited)

MICHALSKA, Hannah

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Farkhatdinov, I., Michalska, H., Berthoz, A., Hayward, V., Modeling verticality estimation during locomotion, Proceedings of the 19th CISM-IFTOMM Symposium on Robot Design, Dynamics, and Control (ROMANSY 2012), Paris, France, 2012, (6 pages).

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PUBLICATIONS - Department of Mechanical Engineering

ANGELES, Jorge

Articles in refereed publications

- 1. Shen, J.J., Kalantari, M., Kövecses, J., Angeles, J. and Dargahi, J., 2012, "Viscoelastic modeling of the contact interaction between a tactile sensor and an atrial tissue," IEEE Transactions on Biomedical Engineering, Vol. 59, No. 6, pp. 1727-1738.
- 2. Taghvaeipour, A, Angeles, J. and Lessard, L., 2012, "Constraint-wrench analysis of robotic manipulators," Multibody system Dynamics, DOI 10.1007/s11044-012-9318-7, 30 pp.
- 3. Javid, F., Angeles, J., Pasini, D. and Cecere, R., 2012, "Shape optimization of a self-deployable anchor designed for percutaneous mitral valve repair," ASME J. Medical Devices, Vol. 6, No. 1, pp. 011003-1-011003-7.
- 4. Zargarbashi, S.S.H., Khan, W.A. and Angeles, J., 2012, "Posture optimization in robot-assisted machining operations," Mechanism and Machine Theory, Vol. 51, pp. 74-86.
- 5. Alizadeh, D., Ma, X.Q. and Angeles, J., 2012, "On the reduction of the normality conditions in equality-constrained optimization problems in mechanics," Meccanica, Vol. 47, pp. 755-768

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- 1. Figliolini, G., Rea, P. and Angeles, J., 2012, "The synthesis of the axodes of spatial four-bar linkages," Proc. ASME 2012 Int. Design Engineering Technical Conferences & Computers and Information in Engineering Conference IDETC/CIE 2012, August 12-15, Chicago, IL, Paper No. DETC2012-71255. This paper received the A.T. Yang Memorial Award in Theoretical Kinematics at the conference.
- 2. Al-Widyan, K.M. and Angeles, J., 2012, "The kinematic synthesis of a robust RCCC mechanism for pick-and-place operations," Proc. ASME 2012 Int. Design Engineering Technical Conferences & Computers and

Information in Engineering Conference IDETC/CIE 2012, August 12-15, Chicago, IL, Paper No.~DETC2012-70878.

3. Azimi, A., Kövecses, J. and Angeles, J., 2011, "Wheel-soil interaction model for rover simulation based on plasticity theory," Proc. 2011 IEEE/RSJ International Conference on Intelligent Robots and Systems IROS 2011, Sept. 25-30, San Francisco, CA, pp. 280-285.

Invited presentations

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Angeles, J., 2012, El Concepto de Complejidad Como Criterio de Diseño en Ingeniería Mecánica (The Concept of Complexity as a Design Criterion in Mechanical Engineering), Keynote Lecture at the XIX National Congress of Mechanical Engineering, sponsored by the Spanish Society of Mechanical Engineering, November 14-16, Castellón de la Plana, Spain.

CORTELEZZI, Luca

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KOVECSES, Jozsef

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- J2. Font-Llagunes, J.M., Barjau, A., Pamies-Vila, R., and Kövecses, J.: "Dynamic Analysis of Impact in Swing-through Crutch Gait Using Impulsive and Continuous Contact Models". Multibody System Dynamics, Vol. 28, No. 3, pp. 257-282, 2012.
- J3. Kalantari, M., Dargahi, J., Kövecses, J., Mardasi, M.G., and Nouri, S.: "A New Approach for Modeling Piezoresistive Force Sensors Based on Semiconductive Polymer Composites". IEEE/ASME Trans. Mechatronics, Vol. 17, No. 3, pp. 572-581, 2012.

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- C2. Shayan Amin, S., Kovacs, L.L., and Kövecses, J.: "Dynamic Behaviour and Stability Analysis of Multibody Haptic Systems", ASME 2012 International Design Engineering Technical Conferences, 1st Biennial International Conference on Dynamics for Design, Chicago, Illinois, August 12-15, 2012.
- C3. Gonzalez, F. and Kövecses, J.: "Load Assessment and Analysis of Impacts in Multibody Systems", The 2nd Joint International Conference on Multibody System Dynamics, Stuttgart, Germany, May 29-June 1, 2012.
- C4. Gonzalez, F. and Kövecses, J.: "Use of Penalty Formulations in the Dynamic Simulation of Redundantly Constrained Multibody Systems", The 2nd Joint International Conference on Multibody System Dynamics, Stuttgart, Germany, May 29-June 1, 2012.
- C5. Ghotbi, B., Gonzalez, F., Kövecses, J. and Angeles, J.: "Vehicle-Terrain Interaction Model for Analysis and Performance Evaluation", The 2nd Joint International Conference on Multibody System Dynamics, Stuttgart, Germany, May 29-June 1, 2012.
- C6. Kovacs, L.L., Bencsik, L. and Kövecses, J.: "Dynamics Analysis of Under-actuated Mechanical Systems for Design Optimization and Control Performance", The 2nd Joint International Conference on Multibody System Dynamics, Stuttgart, Germany, May 29-June 1, 2012.
- C7. Gholami, F., Kövecses, J., and Font-Llagunes, J.M.: "Dynamic Analysis of Foot Models for Human Locomotion", The 2nd Joint International Conference on Multibody System Dynamics, Stuttgart, Germany, May 29-June 1, 2012.
- C8. Azimi, A., Holz, D., Kövecses, J., Angeles, J., and Teichmann, M.: "Efficient Dynamics Modeling for Rover Simulation on Soft Terrain", 50th AIAA Aerospace Sciences Meeting, Nashville, TN, Jan. 9-12, 2012.

NAHON, Meyer

Articles in refereed publications

M. Masciola, M. Nahon and F. Driscoll, 2012, 'Static Analysis of a Lumped Mass Cable System', ASCE Journal of Waterway, Port, Coastal, and Ocean Engineering, Vol. 138, No. 2, pp. 164-171.

Wiens and M. Nahon, 2012, 'Optimally Efficient Swimming in Hyper-Redundant Mechanisms: Control, Design, and Energy Recovery', Bioinspiration & Biomimetics, Vol. 7, No.4, 13 pages.

Other refereed contributions

T. Liesk and M. Nahon, 2012, 'Design and Experimental Validation of a Controller Suite for an Autonomous, Finless Airship', American Control Conference, June 27-29, Montreal.

Invited presentations

Dynamics and Control of Tethered Aerostats', National Renewable Energy Labs, Boulder, Colorado, August 23, 2012

'Dynamics and Control of the Large Adaptive Reflector Multitethered System, National Astronomical Observatories, Chinese Academy of Sciences, Beijing, July 27, 2012

SHARF, Inna

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1. Zarrouk, D., I. Sharf and M. Shoham, "Conditions for Worm-Robot Locomotion in a Flexible Environment: Theory and Experiments," IEEE Transactions on Biomedical Engineering, Vol. 59, No. 4, pp. 1057-1067, 2012.

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- C2. Nguyen Huynh, T.-C. and I. Sharf, "Adaptive Reactionless Motion with Joint Limit Avoidance for Robotic Capture of Unknown Target in Space," Proc. IEEE/RSJ International Conference on Intelligent Robots and Systems, IROS 2012, Algarve, Portugal, October 7-12, 2012.
- C3. Harmat, A., I. Sharf and M. Trentini, "A Hybrid Particle/Grid Wind Model for Realtime Small UAV Flight Simulation," Proc. IEEE/RSJ International Conference on Intelligent Robots and Systems, IROS 2012, Algarve, Portugal, October 7-12, 2012.
- C4. Harmat, A., I. Sharf and M. Trentini, "Parallel Tracking and Mapping with Multiple Cameras on an Unmanned Aerial Vehicle," Proc. Fifth International Conference on Intelligent Robotics and Applications, Montreal, October 3-5, 2012.
- C5. Sharf, I., S. M. Persson, D. St-Onge and N. Reeves, "Development of Aerobots for Satellite Emulation, Architecture and Art," Proc. 13th International Symposium on Experimental Robotics, ISER 2012, Quebec City, USA, June 17-21, 2012.
- C6. Yang, Y., I. Sharf and J. R. Forbes, "Nonlinear Optimal Control of Holonomic Indoor Airship," Best Paper Presentation in the Session, Proc. AIAA Guidance, Navigation and Control Conference, Minneapolis, USA, August 13-16, 2012.
- C7. Persson, S. M. and I. Sharf, "Invariant Momentum-tracking Kalman Filter for Attitude Estimation," Proc. IEEE International Conference on Robotics and Automation, ICRA2012, Saint Paul, Minnesota, USA, May 14-18, 2012.
- C8. Thomson, T., I. Sharf and B. Beckman, "Kinematic Control and Posture Optimization of a Redundantly Actuated Quadruped Robot," Proc. IEEE International Conference on Robotics and Automation, ICRA2012, Saint Paul, Minnesota, USA, May 14-18, 2012.
- C9. Zarrouk, D., I. Sharf and M. Shoham, "Determining the Condition for Crawling on Flexible Surfaces," Proc. IEEE International Conference on Robotics and Automation, ICRA2012, Saint Paul, Minnesota, USA, May 14-18, 2012.
- C10. Turker, K., I. Sharf and M. Trentini, "Step Negotiation with Wheel Traction: A Strategy for a Wheellegged Robot," Proc. IEEE International Conference on Robotics and Automation, ICRA2012, Saint Paul, Minnesota, USA, May 14-18, 2012.

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- C10. Turker, K., I. Sharf and M. Trentini, "Step Negotiation with Wheel Traction: A Strategy for a Wheel-legged Robot," Proc. IEEE International Conference on Robotics and Automation, ICRA2012, Saint Paul, Minnesota, USA, May 14-18, 2012.

PUBLICATIONS- School of Computer Science

DUDEK, Gregory

- **DUDEK, G.** (Girdhar, Y., Xu, A., Shkurti, F., Camillo, J., Higuera, G., Meghjani, M., Giguere, P., Rekleitis, I., **Dudek, G.**) Monitoring Marine Environments using a Team of Heterogeneous Robots, *RSS 2012 Workshop on Robotics for Environmental Monitoring (WREM 2012)*, Sydney, Australia, pp. 1747 1753.
- --(Girdhar,Y., Giguere, P. and **Dudek, G**.) Autonomous Adaptive Underwater Exploration using Online Topic Modelling, *13th International Symposium on Experimental Robotics (ISER 2012)*, Quebec City, Canada.
- --(Meghjani, M. and **Dudek, G.)** Multi-Robot Exploration and Rendezvous on Graphs, *Proceedings of the 2012 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS '12)*, Algarve, Portugal, October 2012, pp. 5270 -5276.
- --(Shkurti, F., Xu, A., Meghjani, M., Camilo, J., Higuera, G., Girdhar, Y., Giguere, P., Dey, B.B., Li, J., Kalmbach, A., Prahacs, C., Turgeon, K., Rekleitis, I. and **Dudek, G.**) Multi-Domain Monitoring of Marine Environments Using a Heterogeneous Robot Team, *Proceedings of the 2012 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS '12)*, Algarve, Portugal, October 2012, pp. 1747 1753.
- --(Gamboa Higuera, J. C., Xu, A., Shkurti, F. and **Dudek, G.**) Socially-Driven Collective Path Planning for Robot Missions, *Proceedings of the 9th Canadian Conference on Computer and Robot Vision (CRV '12)*, Toronto, Canada, May 2012, pp. 417- 424.
- --(Girdhar, Y. and **Dudek, G.)** Efficient on-line data summarization using extremum summaries, *Proceedings of the IEEE International Conference on Robotics and Automation (ICRA2012)*, 2012, pp. 3490-3496.
- --(Xu, A. and **Dudek, G**.) Trust-Driven Interactive Visual Navigation for Autonomous Robots, *Proceedings of the IEEE International Conference on Robotics and Automation (ICRA '12),* St. Paul, USA, May 2012, pp. 392-3929.

KRY, Paul

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- -- (Kry, P. G., Rahgoshay, C., Rabbani, A., Singh, K.), Inverse Kinodynamics: Editing and Constraining Kinematic Approximations of Dynamic Motion, Computers & Graphics, v. 36, n. 8, pp. 904-915, 2012. http://dx.doi.org/10.1016/j.cag.2012.08.010
- -- (Stolpner, S., Kry, P. G., Siddiqi, K.), Medial Spheres for Shape Approximation, IEEE Transactions on Pattern Analysis and Machine Intelligence, v. 34, n. 6, pp. 1234-1240, 2012. DOI: 10.1109/TPAMI.2011.254

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- -- (Andrews, S., Kry, P. G.), Policies for Goal Directed Multi-Finger Manipulation, In 9th Workshop on Virtual Reality Interaction and Physical Simulation (VRIPHYS), pp. 137-145, 2012. (Best paper award) DOI: 10.2312/PE/vriphys/vriphys12/137-145
- -- (Aladdin, R., Kry, P. G.), Static Pose Reconstruction with an Instrumented Bouldering Wall, VRST '12 Proceedings of the 18th ACM symposium on Virtual reality software and technology, pp. 177-184, 2012. doi>10.1145/2407336.2407369
- -- (Wyvill, B., Kry, P. G., Seidel, R., Mould D.), Determining an Aesthetic Inscribed Curve, Computational Aesthetics in Graphics, Visualization, and Imaging, pp. 63-70, 2012. DOI: 10.2312/COMPAESTH/COMPAESTH12/063-070
- -- (Rahgoshay, C., Rabbani, A., Singh, K., Kry, P. G.), Inverse Kinodynamics: Editing and Constraining Kinematic Approximations of Dynamic Motion, Graphics Interface, pp. 185-192, 2012. (Best paper award) http://dl.acm.org/citation.cfm?id=2305276.2305308
- -- (Nunes, R., Cavalcante-Neto, J., Vidal, C., Kry P. G., Zordan V.), Using Natural Vibrations to Guide Control for Locomotion, ACM SIGGRAPH Symposium on Interactive 3D Graphics and Games (I3D), pp. 87-94, 2012 doi>10.1145/2159616.2159631

LANGER, Michael

REFEREED Journals

"Surface visibility in three-dimensional cluttered scenes" M. S. Langer, F. Mannan Journal of the Optical Society of America 29:9, pp. 1794-1807, 2012

"Perception of blending in stereo motion panoramas" V. Couture, M.S. Langer, S. Roy, ACM Transactions on Applied Perception 9(3) July 2012

(Special issue: top five papers from the ACM Symposium on Applied Perception (SAP), Los Angeles, CA, Aug. 2012)

Other publications

"Qualitative shape from shading, specular highlights, and mirror reflections" (Abstract) Michael Langer, Arthur Faisman Vision Sciences Society (VSS), Annual Meeting, Naples Florida May 2012

"Qualitative shape from specular reflections" (Abstract)
Arthur Faisman, Michael Langer
ACM Symposium on Applied Perception (SAP), Los Angeles, CA, Aug. 2012

PINEAU, Joelle

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S. Png, J. Pineau, B. Chaib-draa. "Building adaptive dialogue systems via Bayes-adaptive POMDP". IEEE Journal of Selected Topics in Signal Processing. vol.6(8). pp. 917-927. 2012.

G. Shani, J. Pineau, R. Kaplow. "A survey of point-based POMDP solvers". Autonomous Agents and Multi-Agent Systems. 2012.

51p. DOI 10.1007/s10458-012-9200-2

K. Bush, G. Panuccio, M. Avoli, J. Pineau. "Evidence-based modeling of network discharge dynamics during periodic pacing to control epileptiform activity". Journal of Neuroscience Methods. 2012. vol.204. pp.318-325.

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A.M.S. Barreto, D. Precup, J. Pineau. "On-line reinforcement learning using incremental kernal-based stochastic factorization". Neural Information Processing Systems (NIPS). 2012.

M. M. Fard, Y. Grinberg, J. Pineau, D. Precup, "Compressed Least-Squares Regression on Sparse Spaces", Twenty-Sixth AAAI Conference on Artificial Intelligence (AAAI'12). 2012.

E. Tsang, S. C. W. Ong, J. Pineau. "Design and Evaluation of a Flexible Interface for Spatial Navigation". Canadian Conference on Computer and Robot Vision. 2012.

C. Paduraru, D. Precup, J. Pineau, G. Comanici. "A Study of Off-policy Learning in Computational Sustainability". European Workshop on Reinforcement Learning (EWRL). 2012.

M. M. Fard, Y. Grinberg, J. Pineau, D. Precup. "Bellman Error Based Feature Generation Using Random Projections". European Workshop on Reinforcement Learning (EWRL). 2012.

SIDDIQI, Kaleem

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P. Savadjiev, G. J. Strijkers, A. J. Bakermans, E. Piuze, S. W. Zucker & K. Siddiqi Heart Wall Myofibers are Arranged in Minimal Surfaces to Optimize Organ Function. Proceedings of the National Academy of Science, 109(24):9248-9253, 2012. [PDF] © 2012 by PNAS

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M. Bieth, K. Siddiqi, P. Gravel and A. J. Reader Towards Automated MR-independent Estimation of Neuroreceptor Binding Potential Parametric Maps for PET. In IEEE Nuclear Science Symposium and Medical Imaging Conference (Anaheim, CA). November, 2012. All departments submit an annual report to the university that contains updated information on grants and publications. Please see links below for CIM members and associates.

FACULTY OF SCIENCE

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